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ORIGINAL ARTICLE

NORMING RATES AND LIMIT THEORY FOR SOME TIME-VARYING COEFFICIENT AUTOREGRESSIONS

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A time-varying autoregression is considered with a similarity-based coefficient and possible drift. It is shown that the random-walk model has a natural interpretation as the leading term in a small-sigma expansion of a similarity model with an exponential similarity function as its AR coefficient. Consistency of the quasi-maximum likelihood estimator of the parameters in this model is established, the behaviours of the score and Hessian functions are analysed and test statistics are suggested. A complete list is provided of the normalization rates required for the consistency proof and for the score and Hessian function standardization. A large family of unit root models with stationary and explosive alternatives is characterized within the similarity class through the asymptotic negligibility of a certain quadratic form that appears in the score function. A variant of the stochastic unit root model within the class is studied, and a large-sample limit theory provided, which leads to a new nonlinear diffusion process limit showing the form of the drift and conditional volatility induced by sustained stochastic departures from unity. The findings provide a composite case for time-varying coefficient dynamic modelling. Some simulations and a brief empirical application to data on international Exchange Traded Funds are included.

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1. INTRODUCTION

First-order autoregressions with possible unit roots or roots that are in the vicinity of unity have attracted an enormous amount of interest over recent decades. The literature now provides a near-comprehensive coverage of estimation and testing of the coefficient of the lag-dependent variable in stationary, unit root, explosive and many intermediate cases of near and mild integration, including models with or without fitted intercepts and trends. Traditional analysis of this model relates to DGPs with fixed coefficients that are consistent with a single scenario. For instance, empirical studies frequently work under a null hypothesis that the DGP is a unit root process with drift, not that the process may have fluctuating, time-dependent parameters that are compatible with stationary behaviour for some parts of the sample, unit root behaviour for other parts and mildly explosive behaviour elsewhere. Most econometric software packages include common tests for a unit root, which reflect this characterization. However, recent empirical work, particularly on the global financial crisis, has shown the advantages of working with flexible systems that accommodate multiple regimes of stationary and non-stationary behaviours and transition mechanisms between them (e.g. Phillips, Wu and Yu, 2011; Phillips and Yu, 2011).

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A second trend in the literature involves models with time-varying coefficients, such that the process is at least weakly stationary. See, among others, Nicholls and Quinn (1980, 1981, 1982), Chen and Tsay (1993), Dahlhaus *et al.* (1999), Dahlhaus (2000) and Lundbergh *et al.* (2003). Some related work on explosive random coefficient AR processes has been performed by Hwang and Basawa (2005). In addition, Granger and Swanson (1997) introduced a stochastic unit root (STUR) model where the AR root is in the vicinity of unity, is stochastic and is driven by a stationary process. See also McCabe and Tremayne (1995), Leybourne *et al.* (1996) and McCabe and Smith (1998) for related work on stochastic variability in unit root models. In the latter article, limit theory was presented for the case where the time-varying coefficient decays to unity asymptotically but sufficiently fast that the limit process of the standardized output of the model is unaffected, so that the effects of the stochastic departures from unity have no long-term impact on the process.

Within the context of a wider class of models, the present article considers a variant of the STUR model in which the coefficient of the lag-dependent variable fluctuates forever in a way that ensures the stochastic departures from unity have a long-term impact on the output process. We provide a large-sample limit theory and study the discriminatory power of unit root testing against STUR alternatives. We do not cover in this article an important line of the literature dealing with time-varying coefficient models that are not autoregressions. Those models give rise to issues that are very different from the ones that surface in autoregressions.

Recently, Lieberman (2012) introduced a similarity-based model in the context of time-varying coefficient autoregressions. That article developed the asymptotic theory for quasi-maximum-likelihood estimation (QMLE) of this model and various statistical tests. Unlike earlier literature, the coefficient of the lag-dependent variable in this model can fluctuate freely, and at any specific period t , the process may behave in a stationary, unit root or explosive manner. This feature of the similarity model adds some flexibility to the prominent unit root model, producing a system for which unit root effects may hold on average in a given sample, but not necessarily at all points within the sample.

In this article, we develop the idea further by considering a larger class of models and by showing that the unit root model can be naturally interpreted as a small- σ asymptotic approximation to the similarity model. To fix ideas, we consider the process

$$\begin{aligned} Y_1 &= \mu + \varepsilon_1, \\ Y_t &= \mu + \beta_t(w)Y_{t-1} + \varepsilon_t, t = 2, \dots, n, \end{aligned} \quad (1)$$

where $\mu \in \mathbb{R}$, w is an m -dimensional vector of unknown parameters, assumed to lie in a compact subset of R^m , $\beta_t(w) = \beta_t(x_t, x_{t-1}; w) \in \mathbb{R}_+$, $x_t = (X_{1t}, \dots, X_{mt})'$ is an m -vector of explanatory variables and $\{\varepsilon_t\}$ is a sequence of i.i.d. $(0, \sigma_\varepsilon^2)$ random variables with cumulants κ_r , $r \geq 3$. When there is no risk of ambiguity, we shall simply write σ^2 in place of σ_ε^2 . It is emphasized that μ can be zero or otherwise and that the set of permissible specifications for $\beta_t(x_t, x_{t-1}; w)$ is rich. Moreover, for a given t , $\beta_t(w)$ can be less than, equal to or greater than unity, so that the model can behave in a stationary, unit root or explosive manner over subperiods.

In studying model (1), we prove the consistency of the QMLE of w when $\beta_t(w)$ is allowed to be non-negative, non-stochastic and with $\mu \in \mathbb{R}$. This extends the results of Lieberman (2012) by allowing for the case $\mu = 0$. To achieve the results, we introduce uniform norming factors, which are functions of $n \times n$ matrices, one of which covers the $\mu = 0$ case and another the case $\mu \neq 0$. The behaviours of the score and Hessian functions are analysed, and as with the consistency proof, separate uniform norming factors are given for the $\mu = 0$ case and for the $\mu \neq 0$ case. The simplest scenario, in which $\mu \neq 0$ and the process is approximately a unit root, leads to a score-based test that is asymptotically normal (Lieberman, 2012).

Of particular interest is the model with an exponential similarity function

$$\beta_t(x_t, x_{t-1}; w) = \exp(wu_t), m = 1, \quad (2)$$

where $u_t = \Delta x_t = \Delta X_{1t}$ is the source of variation in the coefficient. If we relax the assumption that $\beta_t(w)$ is non-stochastic (used for the QMLE results) and allow u_t to be i.i.d. random variables, copies of u , so that

$M_u(\omega) = \mathbb{E}(\beta_t)$ is the moment-generating function of u when it exists, then under certain conditions that will be discussed in Section 2,

$$M_u(w) = 1 + O\left((w\sigma_u)^2\right), \quad (3)$$

where $\sigma_u^2 = \text{Var}(u_t)$, $\forall t$. Moreover, the sample path of the coefficient $\beta_t(w)$ has an average that converges pointwise in probability to $M_u(w)$. Thus, on average, the unit root specification, which is believed to be prevalent in economic and financial data, may be interpreted as the leading form in a small- σ expansion of the similarity model, with an error that is of the order $O(\sigma_u^2)$.

A further special case, where the slope coefficient $w = w_n$ in the similarity function (2) is local to zero and is allowed to be endogenous, also approximates a unit root model. This STUR model is analysed by weak convergence methods, and its limit theory is related to that of a local to unity process but gives rise to a new nonlinear diffusion. The properties of this limit process reveal the explicit form of the conditional volatility induced by the similarity function. In many other cases, the distribution theory is much more complicated.

The plan for the article is as follows. In Section 2, we discuss connections and interpretations of the model and show how the random-walk model can be interpreted as a small- σ approximation of the similarity model with an exponential similarity function. Notation and the main results are introduced in Section 3, followed by some discussion in Section 4. Section 5 studies a similarity-based STUR model, its limit theory and the discriminatory power of unit root tests against STUR alternatives. Simulations and an empirical application are provided in Section 6, and Section 7 concludes. All proofs are contained in the Appendix.

2. CONNECTIONS AND INTERPRETATIONS OF THE MODEL

This section draws connections between the similarity model and existing time-series models and provides some insights and interpretations of our approach.

2.1. A Unit Root Model as a Small- σ Approximation to the Similarity Model

Small- σ asymptotics were originally developed by Kadane (1971) to approximate finite-sample distributions in simultaneous equations models to compare k -class estimators in terms of their bias, variance and mean squared error. They may also be used to take expansions about the standard regression model, which applies in a limiting case where the variance of the endogenous regressors tends to zero. A related method was used by Samuelson (1970) to develop quadratic and higher-order approximations useful in portfolio analysis under situations where there is less and less risk.

In the present case, we consider the unit root model as a small- σ approximation of a more general system involving time-varying random coefficients. For the exponential similarity function given in (2), assume that u_t are i.i.d. copies of u , each with a moment-generating function $M_u(w)$, zero mean and small variation, as when it is distributed as $U[-a, a]$, or $N(0, \sigma_u^2)$, with small a or σ_u^2 respectively. The import is that the coefficient of Y_{t-1} varies with u_t but that the fluctuations in the coefficient value are not too large. In the former case, as $\sigma_u^2 = a^2/3$,

$$\begin{aligned} M_u(w) &= \frac{e^{wa} - e^{-wa}}{2wa} \\ &= 1 + \frac{(wa)^2}{6} + \frac{(wa)^4}{120} + O((wa)^6) \\ &= 1 + \frac{(w\sigma_u)^2}{2} + \frac{3(w\sigma_u)^4}{40} + O((wa)^6), \end{aligned} \quad (4)$$

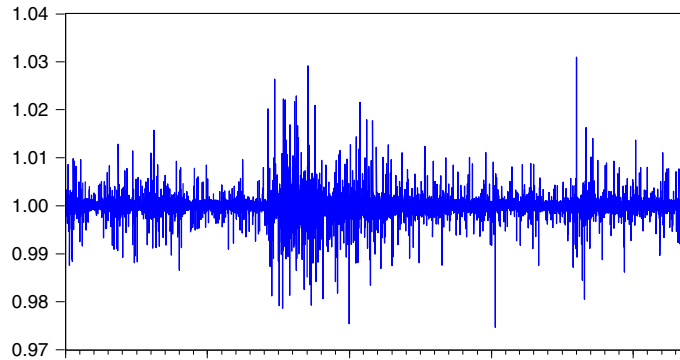


Figure 1. Recursive values of $\hat{\beta}_t$ based on the fitted version of (31)

and the property of the limit shown in (3) follows. In the second case,

$$\begin{aligned}
 M_u(w) &= e^{(w\sigma_u)^2/2} \\
 &= 1 + \frac{(w\sigma_u)^2}{2} + \frac{(w\sigma_u)^4}{8} + O\left((w\sigma_u)^6\right),
 \end{aligned}$$

so that (3) again holds. Of course, in both cases, we can reparametrize with $wu_t = u_t^* \sim U[-w^*, w^*]$, $w^* = wa$ or $u_t^* \sim N(0, w^*)$, $w^* = w\sigma_u$. These choices of β_t are natural and reflect the principle that the average Y_{t-1} coefficient value may be close to unity across the sample but will deviate from unity at any point on the trajectory. In fact, the sample path of the coefficient $\beta_t(w)$ in this setting has an average that converges pointwise in probability to $M_u(w)$. Figure 1 illustrates this point, showing the QMLE of β_t for data on an Australian Exchange Traded Fund (ETF). We emphasize that a limiting case occurs when $x_t = c$, almost surely for all t , so that $u_t = 0$, almost surely, so that there is no random variation in the AR coefficient and the model reduces to a random walk. The unit root model can thus be viewed as a small- σ approximation to a flexible similarity model.

2.2. Capital Asset Pricing Model

The capital asset pricing model (CAPM) has long been central to finance and provides a working foundation for more sophisticated models. Let $\Delta \log Y_t$ be the expected excess return of a certain capital asset and $\Delta \log Z_t$ be the market premium, both at time t . Without the error term, the CAPM relates these quantities through the equation

$$\Delta \log Y_t = \beta \Delta \log Z_t. \tag{5}$$

On rearrangement, the model is

$$Y_t = \exp(\beta \Delta x_t) Y_{t-1},$$

where, in line with our notation so far, $x_t = X_{1t} = \log Z_t$. Thus, the CAPM is just a similarity model with an exponential similarity function in which the value of Y_t is determined by its similarity to Y_{t-1} through the closeness of X_t to X_{t-1} ⁴.

⁴ Strictly speaking, the inclusion of an additive error term in (5) results in the model $Y_t = \exp(\beta \Delta X_t) Y_{t-1} \exp(\varepsilon_t)$ – a similarity model with a multiplicative error term.

2.3. Threshold Autoregression

The threshold case

$$\beta_t(x_t, x_{t-1}; w) = 1\{\|\Delta x_t\| < w_1\} + w_2 1\{\|\Delta x_t\| \geq w_1\},$$

where $\|\cdot\|$ is the Euclidean norm, is of particular interest. Here, Y_{t-1} receives a unit weight in the response only if its characteristics, x_{t-1} , are within the w_1 Euclidean distance from x_t , the characteristics of Y_t . Otherwise, Y_{t-1} is considered to be too 'far' from Y_t and receives only a w_2 weight, where $|w_2| < 1$. This model essentially has the form of a threshold autoregression (e.g. Tong (2011), and the references therein).

3. NOTATION, ASSUMPTIONS AND MAIN RESULTS

This section contains the main theoretical results of the article. Proofs for what follows are given in the Appendix.

Let $C = C(w)$ be an $n \times n$ matrix with entries $[C(w)]_{t,t-1} = \beta_t(x_t, x_{t-1}; w)$, $t = 2, \dots, n$ and $[C(w)]_{i,j} = 0$; otherwise, $x_t = (X_{1t}, \dots, X_{mt})'$ is an m -vector of explanatory variables, I_n be the identity matrix of order n , $S = I_n - C$, $\theta_1 = \sigma^2$, $\theta'_2 = (w_1, \dots, w_m)$, $\theta = (\theta_1, \theta'_2)'$, $y = (Y_1, \dots, Y_n)'$ and $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n)'$. For brevity, we shall write $\beta_t(w)$ in place of $\beta_t(x_t, x_{t-1}; w)$, or simply β_t . The parameter space is given by $\Theta = \Theta_1 \times \Theta_2$, where Θ_1 and Θ_2 are the spaces in which σ^2 and w are assumed to lie respectively. Following convention, the true values of θ , w and μ are denoted θ_0 , w_0 and μ_0 respectively. Similarly, we set $C_0 = C(w_0)$ and $S_0 = I_n - C_0$.

For the $\mu_0 = 0$ case, model (1) can be rewritten as $y = S^{-1}\varepsilon$ and as $\det(S) = 1$, the quasi-log-likelihood function is given by

$$l_n(\theta) = -\frac{n}{2} \log(2\pi\sigma^2) - \frac{y'S'Sy}{2\sigma^2}. \quad (6)$$

For the $\mu_0 \neq 0$ case, we concentrate the quasi-log-likelihood function by using $\hat{\mu}_n(\theta) = 1'S(\theta)y/n$ in place of μ , which leads to

$$(Sy - \hat{\mu}_n(\theta)1)'(Sy - \hat{\mu}_n(\theta)1) = y'S'MSy$$

and therefore,

$$l_n^c(\theta) = -\frac{n}{2} \log(2\pi\sigma^2) - \frac{y'S'MSy}{2\sigma^2}, \quad (7)$$

where $M = I_n - P$, $P = 11'/n$ and $1'$ is an $n \times 1$ (row) vector of 1's. For brevity, $\hat{\theta}_n$ will denote the QMLE of θ using either (6), for the case $\mu_0 = 0$, or (7), for the case $\mu_0 \neq 0$.

By K , we denote a generic bounding constant, independent of n , which may vary from step to step. In the following, we enlist the assumptions used for our model.

Assumption A0: $\{\varepsilon_t\}_{t=1}^n$ is a sequence of i.i.d. continuous random variables, each with a zero mean, variance σ^2 , cumulants κ_r , $r \geq 3$ and a moment-generating function that converges in a narrow strip containing the origin. If $w \neq w'$, $\beta_t(w) \neq \beta_t(w')$, $\forall t$. The matrix $X = (X_{it})_{1 \leq i \leq m, 1 \leq t \leq n}$ is non-stochastic, real and finite.

Assumption A1: There exist σ_L^2 , σ_H^2 , w_L and w_H , such that $\sigma_0^2 \in [\sigma_L^2, \sigma_H^2]$, with $0 < \sigma_L^2 < \sigma_H^2 < \infty$ and for each $i = 1, \dots, m$, $w_{i,0} \in [w_L, w_H]$, with $-\infty < w_L < w_H < \infty$. In addition, $\mu_0 \in R$.

Assumption A2: For all $1 < t \leq n$, the function $\beta_t(w)$ is non-negative, continuous and three times continuously differentiable.

Let $C_0 = C(w_0)$, so that $S_0 = I_n - C_0$. For $r, s, t = 2, \dots, m+1$, set

$$\dot{C}_r(w) = \partial C(w)/\partial \theta_r, \quad \ddot{C}_{r,s}(w) = \partial^2 C(w)/\partial \theta_r \partial \theta_s$$

and

$$\ddot{C}_{r,s,t}(w) = \partial^3 C(w) / \partial \theta_r \partial \theta_s \partial \theta_t.$$

Assumption A3: For all $2 \leq r \leq m + 1, 1 \leq i, j \leq n, w \in \Theta_2 \subset R^m$, there exists a $0 < K_L < \infty$, such that

$$[C]_{i,j} \leq K [C_0]_{i,j},$$

$$K_L [C_0]_{i,j} \leq \left| [\dot{C}_r(w)]_{i,j} \right| \leq K [C_0]_{i,j}.$$

Assumption A4: For all $2 \leq r, s, t \leq m + 1, 1 \leq i, j \leq n, w \in \Theta_2 \subset R^m$, there exists a $0 < K_L < \infty$, such that

$$K_L [C_0]_{i,j} \leq \left| [\ddot{C}_{r,s}(w)]_{i,j} \right| \leq K [C_0]_{i,j}$$

and

$$K_L [C_0]_{i,j} \leq \left| [\ddot{C}_{r,s,t}(w)]_{i,j} \right| \leq K [C_0]_{i,j}.$$

Assumption A0 includes an identification condition and a condition that X is non-stochastic. If $\beta_t = \beta, \forall t$, then these conditions trivially hold. The condition that X is non-stochastic is essential for the results on the QMLE but will be relaxed in Section 5 when a limit theory will be developed for a special case of the model. Assumptions A0–A4 are similar to those of Lieberman (2012), the key difference being that μ_0 is allowed to be zero here. It is trivial to verify that all the assumptions hold for the exponential similarity function, because, if $\beta_t(w) = \exp(\sum_{j=1}^m w_j \Delta X_{tj})$, then $\partial \beta_t(w) / \partial w_j^r = (\Delta X_{tj})^r \beta_t(w)$.

We use the l_1 , spectral and Frobenius norms of an $n \times n$ matrix A , denoted by $\|A\|_1, \|A\|_2$ and $\|A\|_F$ and given by $\|A\|_1 = \sum_{i,j=1}^n |[A]_{i,j}|, \|A\|_2 = (\sup_{|x|=1} x' A x)^{1/2}$ and $\|A\|_F = (\text{tr}(A' A))^{1/2}$. By $O_e(\cdot)$ and $O_{p,e}(\cdot)$ we denote the exact order and exact order in probability respectively (cf. Phillips, 1995).

The following inequalities will be used throughout (see, among others, Graybill, 1983).

$$\begin{aligned} \|A\|_2 &\leq \|A\|_F \leq \sqrt{n} \|A\|_2, \\ x' A x &\leq x' x \|A\|_2, \text{ for } A > 0, | \text{tr}(AB) | \leq \|A\|_F \|B\|_F, \\ \|AB\|_F &\leq \|A\|_2 \|B\|_F, \|AB\|_F \leq \|A\|_F \|B\|_2. \end{aligned} \tag{8}$$

The quantity

$$\rho_n = \frac{\|S_0^{-1}\|_F^2}{\|S_0^{-1'} S_0^{-1}\|_1}$$

turns out to be central to the asymptotic analysis. Terms in the expansions of $l_n(\theta)$ and $l_n^c(\theta)$, the score and Hessian functions based on them, can be conveniently grouped according to the orders of magnitude of powers of ρ_n . As C_0 is non-negative and nilpotent by Assumption A2,

$$S_0^{-1} = I_n + C_0 + \dots + C_0^{n-1},$$

so that all the elements of S_0^{-1} are non-negative. It follows that

$$\|S_0^{-1}\|_F^2 = \sum_{i=1}^n [S_0^{-1'} S_0^{-1}]_{i,i} \leq \sum_{i,j=1}^n [S_0^{-1'} S_0^{-1}]_{i,j} = \|S_0^{-1'} S_0^{-1}\|_1, \tag{9}$$

implying that

$$\rho_n \leq 1. \tag{10}$$

The behaviour of ρ_n has been analysed by Lieberman (2012, Lemma 1) in some leading special cases. In particular, for fixed coefficient stable or explosive autoregressions, ρ_n is bounded from below, whereas for the unit root model, $\rho_n = o(1)$.

The consistency of the QMLE is given in Theorem 1.

Theorem 1. Under Assumptions A0–A3, $\hat{\theta}_n \rightarrow_p \theta_0$.

The requirements for consistency seem quite weak. To establish the asymptotic distribution of the score and the Hessian behaviour, we let D_n and D_n^c be $n \times n$ normalizing matrices corresponding to the $\mu_0 = 0$ and $\mu_0 \neq 0$ cases respectively, such that

$$D_n = \begin{pmatrix} \frac{1}{\sqrt{n}} & 0 & \dots & 0 \\ 0 & \frac{1}{\|S_0^{-1}\|_F} & & \\ \dots & & \dots & \\ 0 & & & \frac{1}{\|S_0^{-1}\|_F} \end{pmatrix}$$

and

$$D_n^c = \begin{pmatrix} \frac{1}{\sqrt{n}} & 0 & \dots & 0 \\ 0 & \frac{1}{\|S_0^{-1'} S_0^{-1}\|_1^{1/2}} & & \\ \dots & & \dots & \\ 0 & & & \frac{1}{\|S_0^{-1'} S_0^{-1}\|_1^{1/2}} \end{pmatrix}.$$

The normalized concentrated score is

$$\begin{aligned} z_n(\theta) &= D_n z_n^*(\theta), \quad z_n^*(\theta) = \frac{\partial l_n(\theta)}{\partial \theta}, \text{ if } \mu_0 = 0, \\ z_n^c(\theta) &= D_n^c \frac{\partial l_n^c(\theta)}{\partial \theta}, \quad z_n^{c*}(\theta) = \frac{\partial l_n^c(\theta)}{\partial \theta}, \text{ if } \mu_0 \neq 0, \end{aligned}$$

with components $z_{nr}(\theta)$ and $z_{nr}^c(\theta)$, $r = 1, \dots, m + 1$. We have

$$z_{n1}(\theta_0) = -\frac{\sqrt{n}}{2\sigma_0^2} + \frac{y' S_0' S_0 y}{2\sigma_0^4 \sqrt{n}}, \mu_0 = 0,$$

and

$$z_{n1}^c(\theta_0) = -\frac{\sqrt{n}}{2\sigma_0^2} + \frac{y' S_0' M S_0 y}{2\sigma_0^4 \sqrt{n}}, \mu_0 \neq 0. \tag{11}$$

For $r = 2, \dots, m + 1$, let $\dot{S}_{0r} = \partial S_0 / \partial \theta_r$,

$$\Lambda_{0r} = \dot{S}_{0r} S_0^{-1} + S_0^{-1'} \dot{S}_{0r}', \tag{12}$$

$$\Gamma_{0r} = M \dot{S}_{0r} S_0^{-1} + S_0^{-1'} \dot{S}'_{0r} M, \tag{13}$$

$$QF_{nr} = \varepsilon' \Lambda_{0r} \varepsilon, \tag{14}$$

$$QF_{nr}^c = \varepsilon' \Gamma_{0r} \varepsilon \tag{15}$$

and

$$LF_{nr}^c = 1' S_0^{-1'} \dot{S}'_{0r} M \varepsilon. \tag{16}$$

The notations QF_{nr} and LF_{nr} stand for the quadratic form and linear form respectively, and when the superscript c is used, it indicates that the score is based on $l_n^c(\theta)$. For $r = 2, \dots, m + 1$ then, we have

$$z_{nr}(\theta_0) = -\frac{QF_{nr}}{2\sigma_0^2 \|S_0^{-1}\|_F}, \mu_0 = 0, \tag{17}$$

$$z_{nr}^c(\theta_0) = -\frac{QF_{nr}^c + 2\mu_0 LF_{nr}^c}{2\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1^{1/2}}, \mu_0 \neq 0, \text{ if } \rho_n = O_e(1) \tag{18}$$

and

$$z_{nr}^c(\theta_0) = -\frac{\mu_0 LF_{nr}^c}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1^{1/2}} + o_p(1), \mu_0 \neq 0, \text{ if } \rho_n = o(1). \tag{19}$$

As is evident from (17)–(19), the leading terms of $z_{nr}(\theta)$ and $z_{nr}^c(\theta)$ depend on both the value of μ_0 and on the order of magnitude of ρ_n . In particular, in the $\mu_0 \neq 0$ case with $\rho_n = o(1)$, the leading term in (19) is linear in ε . This case corresponds, for instance, to a unit root with a drift process. On the other hand, in the $\mu_0 \neq 0$ with $\rho_n = O_e(1)$ case, $z_{nr}^c(\theta)$ ($r = 2, \dots, m + 1$) involves both linear and quadratic forms in ε , so the asymptotic distributions of the score in the two cases are very different.

Theorem 2. Under Assumptions A0–A3, we have the following:

- (1) $z_{n1}(\theta_0)$ and $z_{n1}^c(\theta_0)$ converge in distribution to $N\left(0, \frac{1}{2\sigma_0^4} \left(1 + \frac{\kappa_4}{2\sigma_0^4}\right)\right)$.
- (2) $z_{nr}(\theta_0)$ and $z_{nr}^c(\theta_0)$ are non-negligible, $r = 2, \dots, m + 1$.
- (3) In the case $\mu_0 \neq 0, \rho_n = o(1)$ and a Gaussian ε , $z_{nr}^c(\theta_0)$ is asymptotically normal. In all other cases, $z_{nr}(\theta)$ and $z_{nr}^c(\theta)$ involve quadratic forms in ε .

Since, in general, $z_{nr}(\theta)$ and $z_{nr}^c(\theta)$ involve quadratic forms, their asymptotic distributions cannot be determined without an additional structure on the model. If ε is non-normal, then the leading term of $z_{nr}(\theta_0)$ can be expressed as $\sum_{i=1}^n h_{in} \varepsilon_i$, with weights h_{in} satisfying $\sum_{i=1}^n h_{in}^2 = O_e(1)$. If, in addition, $h_{in} = O(n^{-1})$ for all $i = 1, \dots, n$, then it is straightforward to verify the Lindeberg condition and a Central Limit Theorem (CLT) follows for $z_{nr}(\theta_0)$. However, this requirement cannot be assured in general. For instance, if $h_{1n} = 1$ and $h_{jn} = 0, j = 2, \dots, n$, then $z_{nr}(\theta_0) = -(\mu_0/\sigma_0^2) \varepsilon_1 + o_p(1)$, which is not asymptotically normal. See also Theorem 2 of Lieberman (2012).

Continuing, the normalized Hessian is given by

$$H_n(\theta) = D_n H_n^*(\theta) D_n, H_n^*(\theta) = \frac{\partial^2 l_n(\theta)}{\partial \theta \partial \theta'}, \text{ if } \mu_0 = 0,$$

and

$$H_n^c(\theta) = D_n^c H_n^{c*}(\theta) D_n^c, H_n^{c*}(\theta) = \frac{\partial^2 l_n^c(\theta)}{\partial \theta \partial \theta'}, \text{ if } \mu_0 \neq 0,$$

with components $H_{nr,s}(\theta)$ and $H_{nr,s}^c(\theta)$, $r, s = 1, \dots, m+1$. Let

$$H_{n1,1}(\theta_0) = \frac{1}{2\sigma_0^4} - \frac{y' S_0' S_0 y}{n\sigma_0^6},$$

$$H_{n1,r}(\theta_0) = \frac{\varepsilon' \Lambda_{0r} \varepsilon}{2\sigma_0^4 \sqrt{n} \|S_0^{-1}\|_F}, r = 2, \dots, m+1,$$

$$H_{nr,s}^L(\theta_0) = -\frac{\varepsilon' S_0^{-1} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1}\|_F^2}, r, s = 2, \dots, m+1,$$

$$H_{n1,1}^c(\theta_0) = \frac{1}{2\sigma_0^4} - \frac{y' S_0' M S_0 y}{n\sigma_0^6},$$

$$H_{n1,r}^c(\theta_0) = \frac{\varepsilon' \Gamma_{0r} \varepsilon}{2\sigma_0^4 \sqrt{n} \|S_0^{-1'} S_0^{-1}\|_1^{1/2}}, r = 2, \dots, m+1,$$

$$H_{nr,s}^{c,L_1}(\theta_0) = -\frac{\mu_0^2 1' S_0^{-1} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} 1}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1}, r, s = 2, \dots, m+1,$$

$$H_{nr,s}^{c,L_2}(\theta_0) = -\frac{2\mu_0 1' S_0^{-1'} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1}, r, s = 2, \dots, m+1$$

and

$$H_{nr,s}^{c,L_3}(\theta_0) = -\frac{\varepsilon' S_0^{-1} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1}, r, s = 2, \dots, m+1.$$

Theorem 3. Under Assumptions A0–A4, we have the following:

(1) $H_{n1,1}(\theta_0)$ and $H_{n1,1}^c(\theta_0)$ converge in probability to $-(2\sigma_0^2)^{-1}$, $\forall \mu \in \mathbb{R}$.

For $r = 2, \dots, m+1$, we have the following:

(2) $H_{n1,r}(\theta_0)$ and $H_{n1,r}^c(\theta_0)$ converge in probability to 0, $\forall \mu \in \mathbb{R}$.

(3) $H_{nr,s}(\theta_0) = H_{nr,s}^L(\theta_0) + o_p(1)$, with $H_{nr,s}^L(\theta_0) = O_{p,e}(1)$, if $\mu_0 = 0$.

(4) $H_{nr,s}^c(\theta_0) = H_{nr,s}^{c,L_1}(\theta_0) + H_{nr,s}^{c,L_2}(\theta_0) + H_{nr,s}^{c,L_3}(\theta_0) + o_p(1)$, with $H_{nr,s}^{c,L_1}(\theta_0) = O_{p,e}(1)$, $H_{nr,s}^{c,L_1}(\theta_0) = O_p(\sqrt{\rho_n})$ and $H_{nr,s}^{c,L_3}(\theta_0) = O_{p,e}(\rho_n)$, if $\mu_0 \neq 0$ and $\rho_n = O_e(1)$.

(5) $H_{nr,s}^c(\theta_0) = H_{nr,s}^{c,L_1}(\theta_0) + o_p(1)$, with $H_{nr,s}^{c,L_1}(\theta_0) = O_{p,e}(1)$, if $\mu_0 \neq 0$ and $\rho_n = o(1)$.

We remark that unlike the stationary fixed coefficient case, $H_n(\theta_0)$ may not converge to a fixed matrix. For example, in the $\mu_0 = 0$ and $\beta_t(w) = 1, \forall t$, case, $-H_n(\theta_0)$ converges to the random variable $2\int_0^1 W(r)^2 dr$, (Phillips, 1987, Theorem 3.1). Nevertheless, we may still use Theorems 1–3 to construct hypothesis tests of the form $H_0 : \theta = \theta_0$ by adopting random norming (Heyde, 1975; Feigin, 1976; and Lieberman, 2010, among others). To do so, we recall that by the mean value theorem

$$z_n(\theta_0) = -H_n(\bar{\theta}_n) D_n^{-1} (\hat{\theta}_n - \theta_0), \text{ if } \mu_0 = 0, \tag{20}$$

where $\bar{\theta}_n$ satisfies $\|\bar{\theta}_n - \hat{\theta}_n\| \leq \|\hat{\theta}_n - \theta_0\|$. Let

$$A_n^*(\theta_0) = E_{\theta_0} \left(\frac{\partial l_n(\theta_0)}{\partial \theta} \frac{\partial l_n(\theta_0)}{\partial \theta'} \right)$$

and

$$A_n(\theta_0) = D_n A_n^*(\theta_0) D_n.$$

Multiplying both sides of (20) by $A_n^{-1/2}(\theta_0)$, we obtain

$$A_n^{-1/2}(\theta_0) z_n(\theta_0) = -A_n^{-1/2}(\theta_0) H_n(\bar{\theta}_n) D_n^{-1} (\hat{\theta}_n - \theta_0), \text{ if } \mu_0 = 0, \tag{21}$$

or simply,

$$A_n^{*-1/2}(\theta_0) z_n^*(\theta_0) = -A_n^{*-1/2}(\theta_0) H_n^*(\bar{\theta}_n) (\hat{\theta}_n - \theta_0), \text{ if } \mu_0 = 0, \tag{22}$$

the difference between (21) and (22) being the cancellation of the normalization matrix, D_n . The last equation forms the basis of our test statistic for the hypothesis $H_0 : \theta = \theta_0$. The suggested test is

$$T_n = (\hat{\theta}_n - \theta_0)' H_n^*(\theta_0) (A_n^*(\theta_0))^{-1} H_n^*(\theta_0) (\hat{\theta}_n - \theta_0), \text{ if } \mu_0 = 0.$$

Similarly, for the $\mu \neq 0$ case, the suggested test statistic is

$$T_n^c = (\hat{\theta}_n - \theta_0)' H_n^{c*}(\theta_0) (A_n^{c*}(\theta_0))^{-1} H_n^{c*}(\theta_0) (\hat{\theta}_n - \theta_0),$$

where $H_n^{c*}(\theta_0)$ and A_n^{c*} are analogous to $H_n^*(\theta_0)$ and A_n^* respectively, except that the former is based on $l_n^c(\theta_0)$ in place of $l_n(\theta_0)$ everywhere.

The statistics in (21) and (22) are vectors of normalized quadratic forms with mean zero and unit covariance matrix. In some special cases, such as in the stationary fixed coefficient setting, they are asymptotically $N(0, I_{m+1})$. Note that in the construction of T_n and T_n^c , we have replaced $H_n(\bar{\theta}_n)$ and $H_n^{c*}(\bar{\theta}_n)$ with $H_n^*(\theta_0)$ and $H_n^{c*}(\theta_0)$. The validity of this step requires uniform boundedness of the normalized third-order log-likelihood derivatives, which is given in Lemma 7 of the Appendix. Formally, denote by F_q and F_q^c the asymptotic distributions of the quadratic forms

$$q_n(\theta) = z_n^*(\theta_0)' (A_n^*(\theta_0))^{-1} z_n^*(\theta_0),$$

and

$$q_n^c(\theta) = z_n^{c*}(\theta_0)' (A_n^{c*}(\theta_0))^{-1} z_n^{c*}(\theta_0),$$

respectively. Let

$$b'_{0r} = M \dot{S}_{0r} S_0^{-1} \mathbf{1}.$$

We have the following:

Lemma 4. Under Assumptions A0–A3, we have the following:

$$(1) [A_n]_{1,1} = \frac{1}{2\sigma_0^4} \left(1 + \frac{\kappa_4}{2\sigma_0^4} \right) \text{ and } [A_n^c]_{1,1} = [A_n]_{1,1} + o(1).$$

$$(2) [A_n]_{1,r} = 0 \text{ and } [A_n^c]_{1,r} = o(1), r = 2, \dots, m+1.$$

For $r, s = 2, \dots, m+1$, we have the following:

$$(3) [A_n]_{r,s} = \frac{1}{2} (\text{tr}(\Lambda_{0r} \Lambda_{0s})), \text{ if } \mu_0 = 0.$$

$$(4) \text{ If } \mu_0 \neq 0 \text{ and } \rho_n = O_e(1),$$

$$[A_n^c]_{r,s} = \frac{1}{4\sigma_0^4} \left\{ 2\sigma_0^4 \text{tr}(\Lambda_{0r} \Lambda_{0s}) + \kappa_4 \sum_{i=1}^n [\Gamma_{0r}]_{i,i} [\Gamma_{0s}]_{i,i} + 4\mu_0^2 \sigma_0^2 b'_{0r} b_{0s} \right. \\ \left. + 2\mu_0 \kappa_3 \sum_{i=1}^n ([\Gamma_{0r}]_{i,i} [b_{0s}]_i + [\Gamma_{0s}]_{i,i} [b_{0r}]_i) \right\} + o(1).$$

$$(5) [A_n^c]_{r,s} = \frac{\mu_0^2}{\sigma_0^2} b'_{0r} b_{0s}, \text{ If } \mu_0 \neq 0 \text{ and } \rho_n = o(1).$$

Theorem 5. Under Assumptions A0–A4, the statistics T_n and T_n^c are asymptotically distributed F_q and F_q^c respectively.

To construct a simple test of the form $H_0 : \theta_r = \theta_{0r}$, we may use

$$T_n = \left(\hat{\theta}_{nr} - \theta_{0r} \right)^2 \left[H_n^* (\theta_0) (A_n^* (\theta_0))^{-1} H_n^* (\theta_0) \right]_{r,r}, \text{ if } \mu_0 = 0,$$

or

$$T_n^c = \left(\hat{\theta}_{nr} - \theta_{0r} \right)^2 \left[H_n^{c*} (\theta_0) (A_n^{c*} (\theta_0))^{-1} H_n^{c*} (\theta_0) \right]_{r,r}, \text{ if } \mu_0 \neq 0.$$

The tests can be applied in principle by comparing the calculated T_n or T_n^c values with the simulated p -values of $q_n(\theta_0)$ or $q_n^c(\theta_0)$ respectively.

To complete the limit theory, we provide a consistency theorem for $\hat{\mu}_n$ and discuss its asymptotic distribution.

Theorem 6. Under Assumptions A0–A3, $\hat{\mu}_n \rightarrow_p \mu_0$.

As is clear from the proof of Theorem 6,

$$\sqrt{n} (\hat{\mu}_n - \mu_0) = \frac{1' (C_0 - C(\hat{\theta}_n)) y}{\sqrt{n}} + \sqrt{n} \bar{\varepsilon}_n. \quad (23)$$

Therefore, the asymptotic distribution of $\hat{\mu}_n$ depends critically on the behaviour of the first term on the right-hand side of (23) and may therefore be non-normal. To illustrate, consider the case where $u_t = 1, \forall t, w_0 = 0, \mu_0 = 0$.

It is straightforward to show that in this case,

$$n \left(e^{\hat{w}_n} - 1 \right) \Rightarrow \xi := \frac{\int_0^1 B_\varepsilon(r) dB_\varepsilon(r)}{\int_0^1 B_\varepsilon^2(r) dr - \left(\int_0^1 B_\varepsilon(r) dr \right)^2},$$

where $B_\varepsilon(r)$ is the Brownian motion (BM) associated with the partial sums of the ε_t 's. Therefore, (23) implies that

$$\begin{aligned} \sqrt{n} (\hat{\mu}_n - \mu_0) &= \frac{1}{\sqrt{n}} \sum_{t=1}^{n-1} \left(1 - e^{\hat{w}_n} \right) Y_t + \sqrt{n} \bar{\varepsilon}_n \\ &= -n \left(e^{\hat{w}_n} - 1 \right) \frac{\sum_{t=1}^{n-1} Y_t}{n^{3/2}} + \sqrt{n} \bar{\varepsilon}_n \\ &\Rightarrow -\xi \int_0^1 B_\varepsilon(r) dr + B_\varepsilon(1). \end{aligned}$$

This example illustrates how the asymptotic distribution of $\sqrt{n} (\hat{\mu}_n - \mu_0)$ is generally non-normal and intimately depends on $\hat{\theta}_n$.

4. DISCUSSION

Some of the implications of these findings are as follows.

- (1) The normalization rates required for $l_n(\theta)$ and $l_n^c(\theta)$ in the proof of Theorem 1 are detailed in Table I. For the case $\mu_0 = 0$, we require an $\|S_0^{-1}\|_F^{-2}$ or $\|S_0^{-1'} S_0^{-1}\|_1^{-1}$ normalization when $\rho_n = O_e(1)$ and an $\|S_0^{-1}\|_F^{-2}$ normalization when $\rho_n = o(1)$. In terms of the fixed coefficient framework, as the unit root model is characterized by the condition $\rho_n = o(1)$, an $\|S_0^{-1}\|_F^{-2}$ normalization corresponds to an n^{-2} normalization. For the fixed coefficient stable or explosive AR(1) model, both of which are characterized by $\rho_n = O_e(1)$, an $\|S_0^{-1}\|_F^{-2}$ or $\|S_0^{-1'} S_0^{-1}\|_1^{-1}$ normalization corresponds to an n^{-1} and β^{-2n} normalization in the stable and explosive cases respectively. These rate results are well known (Evans and Savin, 1984; Phillips, 1987; Lieberman, 2012, Lemma 1).
- (2) In the $\mu_0 \neq 0$ case, an $\|S_0^{-1'} S_0^{-1}\|_1^{-1}$ normalization is required for the consistency proof based on $l_n^c(\theta)$, regardless of the order of magnitude of ρ_n . This corresponds to n^{-1} and β^{-2n} normalizations in the stable and explosive cases respectively and an n^{-3} normalization for the unit root model. Thus, unlike the stable and explosive cases in which the normalization is uniform in μ_0 , different normalizations are required for the $\mu_0 = 0$ and $\mu_0 \neq 0$ cases in the unit root case.
- (3) To establish the behaviour of the score, we use the normalizations summarized in Table II. In the $\mu_0 = 0$ case, the score is a scalar multiple of QF_n and needs to be normalized by $\|S_0^{-1}\|_F^{-1}$. In the $\mu_0 \neq 0$ and $\rho_n = O_e(1)$ case, both QF_n^c and LF_n^c are of the same order of magnitude, whereas in the $\mu_0 \neq 0$ and

Table I. Normalization factors for the consistency proof

	Normalization	
	$\mu_0 = 0$	$\mu_0 \neq 0$
$\rho_n = O_e(1)$	$\ S_0^{-1}\ _F^{-2}$ or $\ S_0^{-1'} S_0^{-1}\ _1^{-1}$	$\ S_0^{-1'} S_0^{-1}\ _1^{-1}$
$\rho_n = o(1)$	$\ S_0^{-1}\ _F^{-2}$	$\ S_0^{-1'} S_0^{-1}\ _1^{-1}$

Table II. Normalization factors and dominant terms for the score

	Normalization		Dominant term
	$\mu_0 = 0$	$\mu_0 \neq 0$	
$\rho_n = O_\varepsilon(1)$	$\ S_0^{-1}\ _F^{-1}$	$\ S_0^{-1'} S_0^{-1}\ _1^{-1/2}$	$QF_n + LF_n$
$\rho_n = o(1)$	$\ S_0^{-1}\ _F^{-1}$	$\ S_0^{-1'} S_0^{-1}\ _1^{-1/2}$	LF_n

$\rho_n = o(1)$ case, the term $QF_n / \|S^{-1'} S^{-1}\|_1^{1/2}$ is negligible. As the condition $\rho_n = o(1)$ characterizes a unit root-type process, the vanishing of the latter term is indicative that the process is unit root and not a stable or explosive process. Moreover, since LF_n is the dominant term in the $\mu_0 \neq 0$ and $\rho_n = o(1)$ case, if ε is Gaussian, the normalized score, being linear in ε , is also Gaussian. This is the case discussed by Lieberman (2012). For all other cases, the normalized score involves a quadratic form in ε and therefore is not asymptotically Gaussian. It is clear that in general it is not possible to determine the asymptotic distribution of the normalized score without additional structure on the model, such as the one discussed immediately following Theorem 2.

- (4) In the special case $\mu_0 = 0$ and a (fixed coefficient) unit root model, the normalized score given by $QF_n / \|S_0^{-1}\|_F$ is easily seen to converge to a $(\chi^2(1) - 1)/2$ variate, which agrees with the result of Phillips (1987). See also Lieberman (2010).
- (5) The present QMLE setting assumes non-stochastic regressors. This assumption is common in time-series regression where additional regressors are introduced and occurs in models such as the AR MAX model with exogenous inputs. In the following section, we shall consider a STUR model where the regressors will be allowed to be endogenous.
- (6) We have given an example that shows that the asymptotic distribution of $\sqrt{n}(\hat{\mu}_n - \mu_0)$ may be non-normal. Furthermore, in sufficient generality, the asymptotic distributions of T_n and T_n^c are non-normal. In both cases, simulation-based approaches, such as the bootstrap, can be applied to generate p -values for hypothesis testing.

5. A SIMILARITY STUR MODEL

Here, we weaken the assumption that the regressors are non-stochastic, which is used in the derivation of the results of Section 3, and consider a special case of a similarity autoregression that belongs to a class most closely related to the STUR model studied by Granger and Swanson (1997). The limit theory given here differs from and complements the results given earlier because we allow for endogenous regressors in the similarity function and analyse their impact on the asymptotics. We use the no-intercept similarity autoregression

$$\begin{aligned}
 Y_1 &= \varepsilon_1, \\
 Y_t &= \beta_t(w_n) Y_{t-1} + \varepsilon_t, \quad t = 2, \dots, n,
 \end{aligned}
 \tag{24}$$

with an exponential similarity function $\beta_t(x_t, x_{t-1}; w_n) = e^{w_n u_t}$, where in line with the notation following equation (2), $u_t = \Delta x_t$ is the source of the variation in the AR coefficient. In this formulation, $w_n = \frac{a}{\sqrt{n}}$ is local to zero, so that

$$\beta_t = \exp\left(\frac{a}{\sqrt{n}} u_t\right) = 1 + \frac{a}{\sqrt{n}} u_t + O_p\left(\frac{1}{n}\right) \rightarrow_p
 \tag{25}$$

is local to unity as $n \rightarrow \infty$. However, unlike the usual constant coefficient local to unity model where $\beta = \exp\left(\frac{a}{n}\right) \sim 1 + \frac{a}{n}$, the coefficient is stochastic and may therefore lie in the stationary or the explosive region,

depending on the realization of u_t . Deviations from unity are $O_p(n^{-1/2})$ in this model rather than deterministic and $O(n^{-1})$.

The models (24) and (25) are closely related to the STUR model of Granger and Swanson (1997) in which the AR coefficient has the form $\beta_t = e^{\alpha_t}$, where α_t is generated independently of y_t by a stationary autoregression. Some of the properties of that model were studied by Granger and Swanson, but no limit theory was provided. Related work by McCabe and Tremayne (1995), Leybourne *et al.* (1996) and McCabe and Smith (1998) also considered stochastic variability in a model like (24) and developed asymptotics for tests of difference stationarity based on estimates of the variance of α_t . McCabe and Smith considered (24) with a local AR coefficient of the form $\beta_t = 1 + \xi_{nt}$, where the randomized divergence ξ_{nt} from unity has zero mean and variance $\sigma_{n\xi}^2 = \mathbb{E}(\xi_{nt}^2) = n^{-3/2}\omega^2$ so that $\beta_t = 1 + O_p(n^{-3/4})$. That model transforms to $Y_t = Y_{t-1} + (\varepsilon_t + \xi_{nt}Y_{t-1})$, representing a unit root system with local heteroscedastic integrated errors. McCabe and Smith give limit theory for a test of the hypothesis that $\sigma_{n\xi}^2 = 0$ under the local alternative that $\sigma_{n\xi}^2 = n^{-3/2}\omega^2$. In this model, the decay rate of $\sigma_{n\xi}^2$ to zero (equivalently, the rate of approach of β_t to unity) is sufficiently fast that the limit theory for $n^{-1/2}Y_{\lfloor nr \rfloor}$ is unaffected by local departures $\sigma_{n\xi}^2 > 0$ and the usual BM asymptotics apply. Similarly, the usual (Phillips, 1987) linear diffusion asymptotics apply under fixed $O(n^{-1})$ departures for the AR coefficient $\beta = \exp(\frac{a}{n})$ from unity. In the present work, under (25), the local approach to unity of β_t has rate $O(n^{-1/2})$, which ensures that the standardized output of the process Y_t satisfies a new limit theory, one in which the effects of the stochastic departures from unity have a long-term impact on the process.

Importantly, the stochastic coefficient β_t in (25) is endogenous whenever u_t is correlated with the equation error, that is, when $E(u_t \varepsilon_t) = \sigma_{u\varepsilon} \neq 0$. This correlation turns out to have material consequences in the behaviour of y_t and in its limit theory. With the localizing coefficient $w_n = \frac{a}{\sqrt{n}}$ in the time-varying representation $\beta_t = \exp(w_n \Delta x_t)$, the behaviour of the model is AR in the vicinity of unity and is amenable to functional limit theory, as we show later. This behaviour may be directly analysed as a stochastic alternative to either a unit root model or a constant local to unity model. As we will see, the limit behaviour of the system is a nonlinear diffusion process rather than a linear diffusion process.

We shall assume that the moment-generating function $M_u(s) = \mathbb{E}(e^{su_t})$ of u_t is finite over some interval $s \in (-\delta, \delta)$ of the origin for $\delta > 0$. Solving (24), we have

$$\begin{aligned} Y_t &= \varepsilon_t + \sum_{j=1}^{t-1} \left\{ \prod_{k=0}^{j-1} \beta_{t-k} \right\} \varepsilon_{t-j} = \varepsilon_t + \sum_{j=1}^{t-1} \left\{ \prod_{k=0}^{j-1} e^{\frac{a}{\sqrt{n}} u_{t-k}} \right\} \varepsilon_{t-j} \\ &= \varepsilon_t + \sum_{j=1}^{t-1} \left\{ e^{\frac{a}{\sqrt{n}} \sum_{k=0}^{j-1} u_{t-k}} \right\} \varepsilon_{t-j} = \varepsilon_t + \sum_{s=1}^{t-1} \left\{ e^{\frac{a}{\sqrt{n}} \sum_{\ell=1}^{t-s} u_{s+\ell}} \right\} \varepsilon_s. \end{aligned}$$

Observe that the impulse responses in this system are

$$\frac{\partial Y_t}{\partial \varepsilon_{t-j}} = \prod_{k=0}^{j-1} \beta_{t-k} = e^{\frac{a}{\sqrt{n}} \sum_{k=0}^{j-1} u_{t-k}} = e^{aX_{nj}^u}, \tag{26}$$

where $X_{nj}^u = n^{-1/2} \sum_{k=0}^{j-1} u_{t-k}$ is stochastic and a normalized partial sum process that wanders over \mathbb{R} . Hence, the impulse response function $\frac{\partial Y_t}{\partial \varepsilon_{t-j}} \in \mathbb{R}^+$ and may be arbitrarily small or arbitrarily large, the values being driven by the partial sum process X_{nj}^u .

We assume that partial sums of $\eta_t = (u_t, \varepsilon_t)'$ satisfy the invariance principle $n^{-1/2} \sum_{t=1}^{\lfloor nr \rfloor} \eta_t \Rightarrow B(r) \equiv \text{BM}(\Sigma)$, where $B = (B_u, B_\varepsilon)'$ is a vector BM with positive definite variance matrix $\text{vech}(\Sigma) = (\sigma_u^2, \sigma_{u\varepsilon}, \sigma_\varepsilon^2)$. Then, the asymptotic behaviour of the time series Y_t in (24) has the following form after standardization

$$\begin{aligned}
 n^{-1/2}Y_{\lfloor nr \rfloor} &= n^{-1/2} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{\frac{a}{\sqrt{n}} \sum_{\ell=1}^{\lfloor nr \rfloor - s} u_{s+\ell}} \right\} \varepsilon_s + O_p(n^{-1/2}) \\
 &= n^{-1/2} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{\frac{a}{\sqrt{n}} \sum_{j=s+1}^{\lfloor nr \rfloor} u_j} \right\} \varepsilon_s + O_p(n^{-1/2}) \\
 &= e^{\frac{a}{\sqrt{n}} \sum_{j=1}^{\lfloor nr \rfloor} u_j} \left\{ n^{-1/2} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^s u_j} \right\} \varepsilon_s \right\} + O_p(n^{-1/2}) \\
 &\Rightarrow e^{aB_u(r)} \left\{ \int_0^r e^{-aB_u(p)} dB_\varepsilon(p) - a\sigma_{ue} \int_0^r e^{-aB_u(p)} dp \right\} =: G_a(r).
 \end{aligned}
 \tag{27}$$

The final expression follows by weak convergence of $n^{-1/2} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^s u_j} \right\} \varepsilon_s$ to a stochastic integral accompanied by a stochastic drift, namely,

$$n^{-1/2} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^s u_j} \right\} \varepsilon_s \Rightarrow \int_0^r e^{-aB_u(p)} dB_\varepsilon(p) - a\sigma_{ue} \int_0^r e^{-aB_u(p)} dp,
 \tag{28}$$

a result we now establish. In particular, by factoring the exponential in the summation on the left side of (28), we obtain

$$\begin{aligned}
 \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^s u_j} \right\} \varepsilon_s &= \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} e^{-\frac{a}{\sqrt{n}} u_s} \varepsilon_s \\
 &= \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \left\{ 1 - \frac{a}{\sqrt{n}} u_s + O_p\left(\frac{1}{n}\right) \right\} \varepsilon_s \\
 &= \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \varepsilon_s - \frac{a}{n} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} u_s \varepsilon_s + O_p\left(\frac{1}{\sqrt{n}}\right) \\
 &= \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \varepsilon_s - \frac{a}{n} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \mathbb{E}(u_s \varepsilon_s) \\
 &\quad - \frac{a}{n} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \{u_s \varepsilon_s - \mathbb{E}(u_s \varepsilon_s)\} + O_p\left(\frac{1}{\sqrt{n}}\right) \\
 &= \frac{1}{\sqrt{n}} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} \varepsilon_s - \frac{a\sigma_{ue}}{n} \sum_{s=1}^{\lfloor nr \rfloor - 1} \left\{ e^{-\frac{a}{\sqrt{n}} \sum_{j=1}^{s-1} u_j} \right\} + O_p\left(\frac{1}{\sqrt{n}}\right) \\
 &\Rightarrow \int_0^r e^{-aB_u(p)} dB_\varepsilon(p) - a\sigma_{ue} \int_0^r e^{-aB_u(p)} dp,
 \end{aligned}$$

as required. A related result for the limit of sample covariances involving homogeneous functions (rather than exponentials) of normalized partial sums was proven by Ibragimov and Phillips (2008).

The limit process $G_a(r)$ in (27) is a nonlinear Itô diffusion and satisfies the stochastic differential equation

$$\begin{aligned}
 dG_a(r) &= \left\{ a e^{a B_u(r)} dB_u(r) + \frac{a^2 \sigma_u^2}{2} e^{a B_u(r)} dr \right\} \\
 &\quad \times \left\{ \int_0^r e^{-a B_u(p)} dB_\varepsilon(p) - a \sigma_{ue} \int_0^r e^{-a B_u(p)} dp \right\} \\
 &\quad + e^{a B_u(r)} \left\{ e^{-a B_u(r)} dB_\varepsilon(r) - a \sigma_{ue} e^{-a B_u(r)} dr \right\} \\
 &= a G_a(r) dB_u(r) + dB_\varepsilon(r) + \left[\frac{a^2 \sigma_u^2}{2} G_a(r) - a \sigma_{ue} \right] dr,
 \end{aligned}
 \tag{29}$$

showing the form of the drift and the conditional volatility in the process, which are induced by the similarity function $\beta_t(w_n) = \exp(w_n u_t)$ in (24). Observe that endogeneity (as measured by the correlation σ_{ue}) affects drift both directly and indirectly via $G_a(r)$, whereas volatility is affected only indirectly by σ_{ue} .

If $\sigma_{u\varepsilon} = 0$, B_u is independent of B_ε , and the limit process has the simpler form $G_a(r) = e^{a B_u(r)} \int_0^r e^{-a B_u(p)} dB_\varepsilon(p)$, which is mixed Gaussian with the following covariance kernel conditional on $\mathcal{F}_u = \sigma\{B_u(s) : s \in [0, 1]\}$:

$$\begin{aligned}
 \gamma_{\mathcal{F}_u}(r, s) &= \mathbb{E}\{G_a(r)G_a(s) | \mathcal{F}_u\} \\
 &= e^{a B_u(r)} e^{a B_u(s)} \int_0^r \int_0^s e^{-a B_u(p_1)} e^{-a B_u(p_2)} \mathbb{E}\{dB_\varepsilon(p_1) dB_\varepsilon(p_2)\} \\
 &= \sigma_\varepsilon^2 e^{a B_u(r)} e^{a B_u(s)} \int_0^{r \wedge s} e^{-2a B_u(p)} dp,
 \end{aligned}$$

and unconditional covariance kernel

$$\begin{aligned}
 \gamma(r, s) &= \mathbb{E}\{\gamma_{\mathcal{F}_u}(r, s)\} = \sigma_\varepsilon^2 \mathbb{E}\left\{ e^{a B_u(r) + a B_u(s)} \int_0^{r \wedge s} e^{-2a B_u(p)} dp \right\} \\
 &= \sigma_\varepsilon^2 \int_0^{r \wedge s} \mathbb{E}\left\{ e^{a[B_u(r) - B_u(p)] + a[B_u(s) - B_u(p)]} \right\} dp \\
 &= \sigma_\varepsilon^2 \mathbb{E}\left\{ e^{a[B_u(r \vee s) - B_u(r \wedge s)]} \right\} \int_0^{r \wedge s} \mathbb{E}\left\{ e^{2a[B_u(r \wedge s) - B_u(p)]} \right\} dp \\
 &= \sigma_\varepsilon^2 e^{\frac{1}{2} a^2 (r \vee s - r \wedge s) \sigma_u^2} \int_0^{r \wedge s} e^{2a^2 [r \wedge s - p] \sigma_u^2} dp = \sigma_\varepsilon^2 e^{\frac{1}{2} a^2 (r \vee s - r \wedge s) \sigma_u^2} \left[-\frac{e^{2a^2 [r \wedge s - p] \sigma_u^2}}{2a^2 \sigma_u^2} \right]_0^{r \wedge s} \\
 &= \sigma_\varepsilon^2 \frac{e^{2a^2 \sigma_u^2 r \wedge s} - 1}{2a^2 \sigma_u^2} e^{\frac{1}{2} a^2 \sigma_u^2 (r \vee s - r \wedge s)}.
 \end{aligned}$$

Observe that when $a^2 \sigma_u^2 \rightarrow 0$, $\gamma(r, s) \rightarrow \sigma_\varepsilon^2 (r \wedge s)$, the covariance kernel of the BM B_ε , corresponding to the case where $\beta_t = 1$, $G_a(r) \rightarrow B_\varepsilon(r)$ and (24) is a random walk. Thus, for small $|a|$ or σ_u^2 , the model is local to a simple unit root model. When $a \rightarrow \pm\infty$, the limit behaviour of $Y_{\lfloor nr \rfloor}$ is more complex. In particular, the rates of convergence change, and the limit results become path dependent. This case deserves further study and will be investigated in later work.

If $\sigma_{u\varepsilon} \neq 0$, B_u and B_ε are dependent, and the limit process $G_a(r)$ is no longer conditionally Gaussian. Instead, we have

$$\begin{aligned} G_a(r) &= e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dB_\varepsilon(p) - a\sigma_{u\varepsilon} e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dp \\ &= e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dB_{\varepsilon,u}(p) + \frac{\sigma_{u\varepsilon}}{\sigma_u^2} e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dB_u(p) \\ &\quad - a\sigma_{u\varepsilon} e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dp \\ &=: G_{a,\varepsilon,u}(r) + \frac{\sigma_{u\varepsilon}}{\sigma_u^2} G_{a,u}(r), \end{aligned}$$

where we define

$$\begin{aligned} G_{a,\varepsilon,u}(r) &= e^{aB_u(r)} \int_0^r e^{-aB_u(p)} dB_{\varepsilon,u}(p), \\ G_{a,u}(r) &= e^{aB_u(r)} \left\{ \int_0^r e^{-aB_u(p)} dB_u(p) - a\sigma_u^2 \int_0^r e^{-aB_u(p)} dp \right\}, \end{aligned}$$

and $B_{\varepsilon,u}(r) = B_\varepsilon(r) - \frac{\sigma_{u\varepsilon}}{\sigma_u^2} B_u$ is $\text{BM}(\sigma_{\varepsilon,u}^2)$ with $\sigma_{\varepsilon,u}^2 = \sigma_\varepsilon^2 - \sigma_{u\varepsilon}^2/\sigma_u^2$. The process $G_{a,\varepsilon,u}(r)$ is a conditional Gaussian diffusion with conditional covariance kernel

$$\gamma_{\varepsilon,u,\mathcal{F}_u}(r,s) = \mathbb{E} \{ G_{a,\varepsilon,u}(r) G_{a,\varepsilon,u}(s) | \mathcal{F}_u \} = \sigma_{\varepsilon,u}^2 e^{aB_u(r)} e^{aB_u(s)} \int_0^{r \wedge s} e^{-2aB_u(p)} dp,$$

and unconditional covariance kernel

$$\gamma_{\varepsilon,u}(r,s) = \mathbb{E} \{ G_{a,\varepsilon,u}(r) G_{a,\varepsilon,u}(s) \} = \sigma_{\varepsilon,u}^2 \frac{e^{2a^2\sigma_u^2 r \wedge s} - 1}{2a^2\sigma_u^2} e^{\frac{1}{2}a^2(r \vee s - r \wedge s)\sigma_u^2}.$$

The process $G_{a,u}(r)$ is a nonlinear stochastic integral of B_u with stochastic drift and is obviously non-Gaussian when $a \neq 0$.

For $t = \lfloor nr \rfloor$ for some $r \in (0, 1]$ and large $j = \lfloor n\kappa \rfloor$, $\kappa > 0$, the impulse responses (26) have the form

$$\frac{\partial Y_{\lfloor nr \rfloor}}{\partial \varepsilon_{\lfloor nr \rfloor - \lfloor n\kappa \rfloor}} = \prod_{k=0}^{\lfloor n\kappa \rfloor} \beta_{t-k} = e^{\frac{a}{\sqrt{n}} \sum_{k=0}^{\lfloor n\kappa \rfloor} u_{\lfloor nr \rfloor - k}} \Rightarrow e^{a \int_{r-\kappa}^r dB_u(s)} = e^{a[B_u(r) - B_u(r-\kappa)]},$$

which may be arbitrarily small, close to unity or arbitrarily large depending on the historical trajectory of the process B_u over the past interval $[r - \kappa, r]$.

The functional law (27) enables us to derive the limit behaviour of statistics arising from models (24) and (25). For example, we may consider conventional unit root tests applied to models (24) and (25). Observe that least squares applied to (24) give

$$\begin{aligned} \hat{\beta} &= \frac{\sum_{t=1}^n Y_t Y_{t-1}}{\sum_{t=1}^n Y_{t-1}^2} = \frac{\sum_{t=1}^n e^{\frac{a}{\sqrt{n}} u_t} Y_{t-1}^2}{\sum_{t=1}^n Y_{t-1}^2} + \frac{\sum_{t=1}^n Y_{t-1} \varepsilon_t}{\sum_{t=1}^n Y_{t-1}^2} \\ &= \frac{\sum_{t=1}^n \mathbb{E} \left[e^{\frac{a}{\sqrt{n}} u_t} \right] Y_{t-1}^2}{\sum_{t=1}^n Y_{t-1}^2} + \frac{\sum_{t=1}^n Y_{t-1} \varepsilon_t}{\sum_{t=1}^n Y_{t-1}^2} + \frac{\sum_{t=1}^n \left\{ e^{\frac{a}{\sqrt{n}} u_t} - \mathbb{E} \left[e^{\frac{a}{\sqrt{n}} u_t} \right] \right\} Y_{t-1}^2}{\sum_{t=1}^n Y_{t-1}^2} \\ &= M \left(\frac{a}{\sqrt{n}} \right) + \frac{\sum_{t=1}^n Y_{t-1} \varepsilon_t}{\sum_{t=1}^n Y_{t-1}^2} + \frac{\sum_{t=1}^n \left\{ e^{\frac{a}{\sqrt{n}} u_t} - M \left(\frac{a}{\sqrt{n}} \right) \right\} Y_{t-1}^2}{\sum_{t=1}^n Y_{t-1}^2}, \end{aligned}$$

so that

$$n \left[\hat{\beta} - M \left(\frac{a}{\sqrt{n}} \right) \right] = \frac{n^{-1} \sum_{t=1}^n Y_{t-1} \varepsilon_t}{n^{-2} \sum_{t=1}^n Y_{t-1}^2} + \frac{n^{-1} \sum_{t=1}^n \left\{ e^{\frac{a}{\sqrt{n}} u_t} - M \left(\frac{a}{\sqrt{n}} \right) \right\} Y_{t-1}^2}{n^{-2} \sum_{t=1}^n Y_{t-1}^2}.$$

By standard weak convergence arguments, we have

$$\frac{n^{-1} \sum_{t=1}^n Y_{t-1} \varepsilon_t}{n^{-2} \sum_{t=1}^n Y_{t-1}^2} \Rightarrow \frac{\int_0^1 G_a(r) dB_\varepsilon(r)}{\int_0^1 G_a(r)^2 dr}.$$

Expanding the moment-generating function gives

$$\begin{aligned} \eta_{n,t}(a) &= e^{\frac{a}{\sqrt{n}} u_t} - M \left(\frac{a}{\sqrt{n}} \right) \\ &= \left\{ 1 + \frac{a}{\sqrt{n}} u_t + \frac{1}{2} \left(\frac{a}{\sqrt{n}} \right)^2 u_t^2 \right\} - \left\{ 1 + \frac{1}{2} \left(\frac{a}{\sqrt{n}} \right)^2 \sigma_u^2 \right\} + o_p(n^{-1}) \\ &= \frac{a}{\sqrt{n}} u_t + \frac{a^2}{2n} (u_t^2 - \sigma_u^2) + o_p(n^{-1}), \end{aligned}$$

so that by standard arguments,

$$\begin{aligned} \frac{n^{-1} \sum_{t=1}^n Y_{t-1}^2 \eta_{n,t}(a)}{n^{-2} \sum_{t=1}^n Y_{t-1}^2} &\sim a \frac{\sum_{t=1}^n \left(\frac{Y_{t-1}}{\sqrt{n}} \right)^2 \frac{u_t}{\sqrt{n}}}{n^{-1} \sum_{t=1}^n \left(\frac{Y_{t-1}}{\sqrt{n}} \right)^2} + O_p(n^{-1/2}) \\ &\Rightarrow a \frac{\int_0^1 G_a(r)^2 dB_u(r)}{\int_0^1 G_a(r)^2 dr}, \end{aligned}$$

which leads to the limit theory

$$n \left[\hat{\beta} - M \left(\frac{a}{\sqrt{n}} \right) \right] \Rightarrow \frac{\int_0^1 G_a(r) dB_\varepsilon(r)}{\int_0^1 G_a(r)^2 dr} + a \frac{\int_0^1 G_a(r)^2 dB_u(r)}{\int_0^1 G_a(r)^2 dr}.$$

Correspondingly, with unit root centring, we have

$$n \left[\hat{\beta} - 1 \right] \Rightarrow \frac{1}{2} a^2 \sigma_u^2 + \frac{\int_0^1 G_a(r) dB_\varepsilon(r)}{\int_0^1 G_a(r)^2 dr} + a \frac{\int_0^1 G_a(r)^2 dB_u(r)}{\int_0^1 G_a(r)^2 dr}. \tag{30}$$

It follows that standard coefficient-based unit-root (UR) tests have only local discriminatory power against a stochastic UR of the form (24). Similar results apply for t -ratio-based and other UR tests. Observe that as $|a| \rightarrow \infty$, (30) is dominated by the first term on the right side, and a rejection of a UR occurs on the right side of unity corresponding to explosive alternatives. It follows that in the similarity models (24) and (25), deviations from a UR in the explosive direction dominate the limit behaviour of the UR test statistic.

6. SIMULATIONS AND EMPIRICS

6.1. Simulations

To evaluate the behaviour of the estimators, simulations were conducted on the model (1) with $\beta_t = \exp(wZ_t)$ for $n = 250, 500$ and 1000 , $\mu = 0, 0.25$ and $w = 0.07$ and 0.2 , with 2000 replications per experiment. In one setting, we took $Z_t \sim NID(-w/2, 1)$, and in the other, we took $Z_t \sim U[-1, 1] + b_w$, $b_w = -0.0116648$ if $w = 0.07$ and $b_w = -0.033289$ if $w = 0.2$. With these choices, $\mathbb{E}_Z(\beta_t) = 1, \forall t$, but for each t , β_t can be greater than, equal to or less than unity. Means and standard deviations of $\hat{w}_n, \hat{\mu}_n$ and $\hat{\beta}_t$ for all the scenarios considered here are summarized in Tables III and IV.

Overall, with no noticeable differences between the cases, the means are very close to the true values, and the estimated standard deviations decline with n , as is expected, corroborating consistency.

6.2. Financial Data Application

For illustration, we consider eight country ETFs, denoted by P_t , traded in the USA and measured in 15-min intervals. The model is

$$P_t = \exp\{\Delta NAV_t (w_1 + w_2 D_t) + \Delta SP_t (w_3 + w_4 D_t) + ECT_{t-1} (w_5 + w_6 D_t)\} P_{t-1} + \varepsilon_t, \quad (31)$$

Table III. Performance of the model estimators

n	\hat{w}		$\hat{\mu}$		$\hat{\beta}_t$	
	Mean	SD	Mean	SD	Mean	SD
$\mu = 0, w = 0.07$						
250	0.0696	0.0164	-0.0010	0.0624	1.0000	0.0027
500	0.0702	0.0082	0.0001	0.0448	1.0000	0.0018
1000	0.0699	0.0042	-0.0006	0.0318	1.0000	0.0013
$\mu = 0, w = 0.2$						
250	0.1998	0.0170	0.0023	0.0632	0.9996	0.0074
500	0.1998	0.0093	0.0007	0.0448	0.9997	0.0052
1000	0.2001	0.0048	0.0000	0.0309	0.9999	0.0037
$\mu = 0.25, w = 0.07$						
250	0.0701	0.0038	0.2500	0.0626	1.0000	0.0026
500	0.0700	0.0013	0.2496	0.0450	1.0000	0.0018
1000	0.0700	0.0005	0.2501	0.0326	1.0000	0.0013
$\mu = 0.25, w = 0.2$						
250	0.1998	0.0053	0.2513	0.0630	0.9999	0.0074
500	0.2000	0.0021	0.2523	0.0447	1.0001	0.0052
1000	0.2000	0.0010	0.2501	0.0316	1.0001	0.0036

$Z_t \sim U[-1, 1] + b_w$, where $b_w = -0.0116648$ if $w = 0.07$ and $b_w = -0.033289$ if $w = 0.2$.

Table IV. Performance of the model's estimators

<i>n</i>	\hat{w}		$\hat{\mu}$		$\hat{\beta}_t$	
	Mean	SD	Mean	SD	Mean	SD
$\mu = 0, w = 0.07$						
250	0.0700	0.0094	-0.0010	0.0630	0.9999	0.0044
500	0.0698	0.0050	-0.0009	0.0457	0.9999	0.0031
1000	0.0700	0.0023	-0.0009	0.0324	1.0000	0.0022
$\mu = 0, w = 0.2$						
250	0.1996	0.0106	0.0026	0.0629	0.9998	0.0128
500	0.1997	0.0052	-0.0004	0.0454	0.9998	0.0091
1000	0.1999	.0027	-0.0002	0.0321	1.0000	0.0064
$\mu = 0.25, w = 0.07$						
250	0.0700	0.0026	0.2485	0.0638	1.0000	0.0045
500	0.0700	0.0010	0.2507	0.0460	0.9999	0.0032
1000	0.0700	0.0004	0.2494	0.0315	1.0000	0.0022
$\mu = 0.25, w = 0.2$						
250	0.2000	0.0043	0.2514	0.0636	0.9999	0.0128
500	0.1999	0.0019	0.2501	0.0436	0.9998	0.0093
1000	0.1999	0.0009	0.2499	0.0322	1.0001	0.0063

$Z_t \sim NID(\mu_Z, 1)$ with $\mu_Z = -w/2$.

Table V. *p*-Values of the ADF tests for the exchange traded fund data

	Ticker							
	EWA (Australia)	EWH (Hong Kong)	EWJ (Japan)	EWM (Malaysia)	EWS (Singapore)	EWT (Taiwan)	EWY (South Korea)	FXI (China)
Intercept	0.1800	0.7910	0.6403	0.7002	0.6105	0.6142	0.0675	0.3243
None	0.5913	0.6190	0.6109	0.8491	0.8078	0.6400	0.8034	0.8596

Note: Intercept denotes an ADF test with an intercept; None denotes an ADF test without a trend or an intercept.

where NAV_t is the net asset value, SP_t is the S&P500 index, ECT_t is an error correction term equal to $P_t - NAV_t$, D_t is a dummy variable, taking the value of unity if t is the US market-open time and zero otherwise, and all variables (apart from D_t) were transformed by a natural logarithm. The data are available for Australia, Hong Kong, Japan, Malaysia, Singapore, Taiwan, South Korea and China. The tickers for these countries are given by EWA, EWH, EWJ, EWM, EWS, EWT, EWY and FXI respectively. The sample range is 15/12/2000–13/12/2010, apart for China, where it is available for 8/10/2004–13/12/2010. The data are discussed in detail by Levy and Lieberman (2013).

Unit root tests for P_t with and without a constant are reported in Table V. As expected, the *p*-values in all cases are very high, and they are generally higher for the version of the ADF test, which does not include a constant. Thus, the (fixed coefficient) unit root null hypothesis cannot be rejected, although the underlying process may well include a volatile lag-dependent variable coefficient.

The estimated model results are given in Table VI, with M1 and M2 denoting the unit root with a drift model and model (31) respectively. For the former, the slope coefficient equals unity to the third decimal place throughout, whereas the drift parameter is very small with large standard errors. Thus, a driftless unit root model seems to be a reasonable approximation to the DGP. Nevertheless, the average Akaike information criterion for M1 equals -7.949, whereas for M2, it is -9.618. To the third decimal place, the Schwarz criterion averages are almost identical to the Akaike information criterion averages and are therefore omitted.

Table VI. Similarity-based model estimation of the exchange traded fund data

Ticker		$\hat{\mu}$	\hat{w}_1	\hat{w}_2	\hat{w}_3	\hat{w}_4	\hat{w}_5	\hat{w}_6	AIC
EWA (Australia)	M1	0.001 (0.0004)	1.000 (0.0001)						-7.625
	M2		0.269 (0.0033)	0.001 (0.0036)	0.283 (0.0018)	0.017 (0.0032)	-0.003 (0.0004)	-0.251 (0.0019)	-9.903
EWH (Hong Kong)	M1	0.000 (0.0003)	1.000 (0.0001)						-8.010
	M2		0.040 (0.0026)	0.244 (0.0026)	0.374 (0.0019)	-0.053 (0.0035)	-0.003 (0.0004)	-0.241 (0.0018)	-9.668
EWJ (Japan)	M1	0.000 (0.0002)	1.000 (0.0000)						-8.779
	M2		0.213 (0.0037)	0.072 (0.0040)	0.336 (0.0017)	0.054 (0.0028)	-0.002 (0.0003)	-0.237 (0.0016)	-10.180
EWM (Malaysia)	M1	0.000 (0.0003)	1.000 (0.0001)						-8.144
	M2		0.031 (0.0109)	0.329 (0.0114)	0.339 (0.0032)	-0.082 (0.0055)	-0.008 (0.0007)	-0.236 (0.0035)	-9.196
EWS (Singapore)	M1	0.001 (0.0005)	1.000 (0.0002)						-7.583
	M2		0.104 (0.0141)	0.299 (0.0144)	0.424 (0.0030)	-0.165 (0.0059)	-0.007 (0.0008)	-0.348 (0.0035)	-9.575
EWT (Taiwan)	M1	0.000 (0.0003)	1.000 (0.0001)						-7.958
	M2		0.0258 (0.0082)	0.275 (0.0084)	0.399 (0.0025)	0.042 (0.0044)	-0.004 (0.0004)	-0.204 (0.0020)	-9.335
EWY (South Korea)	M1	0.001 (0.0004)	1.000 (0.0001)						-7.773
	M2		0.004 (0.0023)	0.202 (0.0026)	0.281 (0.0016)	0.008 (0.0030)	-0.001 (0.0003)	-0.159 (0.0013)	-9.370
FXI (China)	M1	0.002 (0.0008)	1.000 (0.0002)						-7.722
	M2		0.010 (0.0170)	0.189 (0.0170)	0.332 (0.0017)	-0.061 (0.0034)	-0.001 (0.0003)	-0.166 (0.0017)	-9.715

Note: M1 is the random walk with a drift model; for M1, $\hat{w}_1 \equiv \hat{\beta}$; M2 is the similarity model (31); standard errors are in brackets.

Across all cases, the error correction coefficient estimates \hat{w}_5 and \hat{w}_6 are negative, with cross-country sample averages equal to -0.004 and -0.230 respectively. These results imply that, *ceteris paribus*, when the error correction term is positive so that $P_{t-1} > NAV_{t-1}$, there will be a downward correction to P_t . The model thus has a time-varying coefficient together with an embedded error correction mechanism that is a nonlinear driver of the coefficient of the lag-dependent variable.

The graph of $\hat{\beta}_t$ for EWA is displayed in Figure 1, exhibiting volatility and fluctuating around unity, as expected. Other cases look very similar. Finally, the standard errors are based on Eviews' calculation of the outer products of the score and are only indicative for this application. In principle, the suggested test procedure can be applied and compared with bootstrapped p -values. Overall, the random-walk model appears to be a reasonable approximation to (31), but it does not reflect any of the period-by-period variation captured in Figure 1 or potential drivers of that variation.

7. CONCLUSIONS

We investigated time-varying autoregressions in which variation in the coefficient of the lag-dependent variable is driven by a similarity function. A key feature of this model is that the slope coefficient can be equal to, less than or greater than unity at any point in time, giving the model a high degree of flexibility in the AR response.

Consistency of the QMLE of the parameter vector was established together with a complete taxonomy of the required norming rates and standardization of the score and Hessian functions for the different cases. A related similarity system involving a local to unity STUR model was introduced, and a new limit theory was established in which the limit process, $G_a(r)$, in this system is a nonlinear Itô diffusion process. The similarity function impacts this model by inducing drift and conditional volatility in the limit process, showing how the flexible AR response in a STUR system can be the source of both drift and volatility.

Our simulations show that the QMLE performs well for sample sizes ranging from 250 to 1000. The model is illustrated empirically in an application to international ETF data. While a unit root model is not rejected, the time-varying coefficient characteristics of the AR responses are vividly apparent in the sample data, showing both mildly explosive and mildly integrated realizations. These findings provide a combined case, involving both theory and empirics, that showcases the advantages of time-varying coefficient dynamic modelling.

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APPENDIX

Proof of Theorem 1

The proof for the case $\mu_0 \neq 0$ was given by Lieberman (2012). The case $\mu_0 = 0$ requires a different normalization, and we deal with it here. For any $\delta_1 > 0$, denote by $B_{\delta_1}(\theta_0)$ the ball $\{\theta \in \Theta : \|\theta - \theta_0\| \leq \delta_1\}$ and by $B_{\delta_1}^c(\theta_0)$ the complement of $B_{\delta_1}(\theta_0)$ in Θ . Using Wu’s (1981) criterion, it is sufficient to show that $\forall \delta_1 > 0$,

$$\lim_{n \rightarrow \infty} \inf_{B_{\delta_1}^c(\theta_0)} n^{-1} (l_n(\sigma_0^2, \theta'_{20}) - l_n(\sigma^2, \theta'_{20})) \tag{A.1}$$

and

$$\lim_{n \rightarrow \infty} \inf_{B_{\delta_1}^c(\theta_0)} \|S_0^{-1}\|_F^{-2} (l_n(\sigma_0^2, \theta'_{20}) - l_n(\sigma^2, \theta'_{20})) \tag{A.2}$$

are strictly positive in probability. Now,

$$\mathbb{E}_{\theta_0} (n^{-1} l_n(\sigma^2, \theta'_{20})) = -\frac{1}{2} \log(2\pi\sigma^2) - \frac{\sigma_0^2}{2\sigma^2},$$

and

$$\text{Var}_{\theta_0} (n^{-1} l_n(\sigma^2, \theta'_{20})) = \frac{1}{2\sigma^4 n} \left(\sigma_0^4 + \frac{\kappa_4}{2} \right).$$

Hence,

$$n^{-1} (l_n(\sigma_0^2, \theta_{20}) - l_n(\sigma^2, \theta'_{20})) \rightarrow_p \frac{1}{2} \left(\frac{\sigma_0^2}{\sigma^2} - 1 - \log \left(\frac{\sigma_0^2}{\sigma^2} \right) \right) \geq 0,$$

with equality if and only if $\sigma^2 = \sigma_0^2$.

To establish (A.2), we use the decomposition

$$\begin{aligned} (l_n(\sigma_0^2, \theta'_{20}) - l_n(\sigma^2, \theta'_{20})) &= \frac{1}{2\sigma_0^2} (y' S' S y - y' S_0 S_0 y) \\ &= \frac{1}{2\sigma_0^2} y' S'_0 (S_0^{-1'} G' + G S_0^{-1}) S_0 y + \frac{1}{2\sigma_0^2} y' G' G y, \\ &= Q_{1n} + Q_{2n}, \end{aligned} \tag{A.3}$$

say, where $G = S - S_0$. We have

$$Q_{1n} = O_p \left(\|S_0^{-1}\|_F \right). \tag{A.4}$$

Considering Q_{2n} , we have

$$\mathbb{E}_{\theta_0} (y'G'Gy) = \mathbb{E}_{\theta_0} (\varepsilon' S_0^{-1'} G' G S_0^{-1} \varepsilon) \leq K \|S_0^{-1}\|_F^2,$$

and

$$\text{Var}_{\theta_0} (y'G'Gy) \leq K \|S_0^{-1}\|_F^4$$

so that

$$Q_{2n} = O_p \left(\|S_0^{-1}\|_F^2 \right).$$

To complete the proof, we see that $Q_{2n} \geq 0$, because $G'G$ is positive semidefinite. Now, with $g_{\min} = \min_{2 \leq i \leq n} [G]_{i,i-1}$,

$$\begin{aligned} \frac{\mathbb{E}_{\theta_0} (\varepsilon' S_0^{-1'} G' G S_0^{-1} \varepsilon)}{\|S_0^{-1}\|_F^2} &= \frac{\sigma_0^2 \text{tr} (S_0^{-1'} G' G S_0^{-1})}{\|S_0^{-1}\|_F^2} \\ &= \frac{\sigma_0^2 \|G S_0^{-1}\|_F^2}{\|S_0^{-1}\|_F^2} \\ &\geq \sigma_0^2 g_{\min}^2 \frac{\sum_{i,j=1}^{n-1} [S_0^{-1}]_{i,j}^2}{\sum_{i,j=1}^n [S_0^{-1}]_{i,j}^2} \\ &\geq K_L, \end{aligned}$$

for some $K_L > 0$, which is independent of n . As $\|S_0^{-1}\|_F^2 \geq n$, Q_{2n} strictly dominates Q_{1n} , and because y is continuous, $Q_{2n} \geq 0$ and $\mathbb{E}_{\theta_0} (Q_{2n} / \|S_0^{-1}\|_F^2) > 0$, $Q_{2n} / \|S_0^{-1}\|_F^2$ is strictly positive in probability uniformly in $B_{\delta_1}^c(\theta_0)$, as required. □

Proof of Theorem 2

Case 1: $\mu_0 = 0$. The score with respect to σ^2 is given by

$$z_{n1}(\theta_0) = -\frac{\sqrt{n}}{2\sigma_0^2} + \frac{y' S_0' S_0 y}{2\sigma_0^4 \sqrt{n}}. \tag{A.5}$$

Hence,

$$\mathbb{E}_{\theta_0} (z_{n1}(\theta_0)) = 0,$$

and

$$\text{Var}_{\theta_0} (z_{n1}(\theta_0)) = \frac{1}{2\sigma_0^4} \left(1 + \frac{\kappa_4}{2\sigma_0^4} \right). \tag{A.6}$$

Higher-order cumulants of $z_{n1}(\theta_0)$ tend to zero, so part 1 of the Theorem is done. For $r = 2, \dots, m + 1$,

$$\begin{aligned} \frac{\partial l_n(\theta_0)}{\partial \theta_r} &= -\frac{y'(\dot{S}'_{0r}S_0 + S'_0\dot{S}_{0r})y}{2\sigma_0^2} \\ &= -\frac{\varepsilon'(\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r})\varepsilon}{2\sigma_0^2}. \end{aligned} \tag{A.7}$$

It follows that

$$\varepsilon'(\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r})\varepsilon = O_p(\|S_0^{-1}\|_F). \tag{A.8}$$

By Assumption A3,

$$\|\dot{C}_{0r}S_0^{-1}\|_F \geq K_L \|S_0^{-1} - I_n\|_F.$$

Hence,

$$\begin{aligned} \frac{\|S_0^{-1}\|_F^2}{\text{tr}(S_0^{-1'}\dot{S}'_{0r}\dot{S}_{0r}S_0^{-1})} &= \frac{\|S_0^{-1}\|_F^2}{\|\dot{S}_{0r}S_0^{-1}\|_F^2} \\ &\leq K_L \frac{\|S_0^{-1}\|_F^2}{\|S_0^{-1} - I\|_F^2} \\ &= K_L \frac{\sum_{i,j=1}^n [C_0 + \dots + C_0^{n-1}]_{i,j}^2 + n}{\sum_{i,j=1}^n [C_0 + \dots + C_0^{n-1}]_{i,j}^2} \\ &< K_L \left(1 + \frac{n}{\sum_{i,j=1}^n [C_0]_{i,j}^2} \right) \\ &\leq K. \end{aligned}$$

Therefore, there exists a c , such that

$$\frac{1}{\|S_0^{-1}\|_F^2} \text{Var}_{\theta_0}(\varepsilon'(\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r})\varepsilon) > c > 0,$$

implying that the required normalization for $\partial l_n(\theta_0)/\partial \theta_r, r = 2, \dots, m + 1$, is $\|S_0^{-1}\|_F^{-1}$.

Case 2: $\mu_0 \neq 0$. The score with respect to (w.r.t.) σ^2 has been dealt with by Lieberman (2012). The concentrated score w.r.t. $\theta_r, r = 2, \dots, m + 1$, is given by

$$\frac{\partial l_n^c(\theta_0)}{\partial \theta_r} = -\frac{1}{2\sigma_0^2} (QF_n^c + 2\mu_0 LF_n^c), \tag{A.9}$$

where QF_n^c and LF_n^c are given by (15) and (16). We know from Lieberman (2012) that

$$QF_{nr}^c = O_p(\|S_0^{-1}\|_F) \tag{A.10}$$

and that

$$LF_{nr}^c = O_p(\|S_0^{-1'}S_0^{-1}\|_1^{1/2}). \tag{A.11}$$

Therefore, we need to distinguish between two subcases.

Subcase 2(i): $\rho_n = O_e(1)$. In this subcase, we can normalize the score by $\|S_0^{-1'}S_0^{-1}\|_1^{-1/2}$ to obtain

$$z_{nr}^c(\theta_0) = O_p(1) + O_p(\sqrt{\rho_n}).$$

However, in this case, $O_{p,e}(\sqrt{\rho_n}) = O_{p,e}(1)$, and because $\|S_0^{-1}\|_F \geq K_L \|S_0^{-1'}S_0^{-1}\|_1^{1/2}$, for some $1 > K_L > 0$, obtaining the lower bound on the variance of $QF_n^c / \|S_0^{-1'}S_0^{-1}\|_1^{1/2}$ is similar to the derivation of the lower bound in the $\mu_0 = 0$ case, and therefore, this subcase is done.

Subcase 2(ii): $\rho_n = o(1)$. By (A.9)–(A.11), in this subcase,

$$z_{nr}^c(\theta_0) = \frac{LF_n^c}{\|S_0^{-1'}S_0^{-1}\|_1^{1/2}} + o_p(1).$$

The lower bound on $LF_n^c / \|S_0^{-1'}S_0^{-1}\|_1^{1/2}$ was established by Lieberman (2012), and therefore, the proof of Theorem 2 is completed. □

Proof of Theorem 3

Case 1: $\mu_0 = 0$. It is straightforward to verify part (1) of the theorem for this case. Part (2) is established on the observation that

$$E_{\theta_0}(\varepsilon'(\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r})\varepsilon) = 0$$

and

$$\begin{aligned} \text{Var}_{\theta_0}(\varepsilon'(\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r})\varepsilon) &= 4\sigma_0^4 \text{tr}(S_0^{-1'}\dot{S}'_{0r}\dot{S}_{0r}S_0^{-1}) \\ &\quad + \kappa_4 \sum [\dot{S}_{0r}S_0^{-1} + S_0^{-1'}\dot{S}'_{0r}]_{i,i}^2 \\ &\leq 4\sigma_0^4 \|S_0^{-1}\|_F^2 \sup_t \hat{\beta}_{0t}^2 \\ &\leq K \|S_0^{-1}\|_F^2, \end{aligned}$$

because $\dot{S}_{0r}S_0^{-1}$ has zero diagonal elements. For $2 \leq r, s \leq m + 1$,

$$\begin{aligned} H_{nr,s}(\theta_0) &= -\frac{y'(\ddot{S}'_{0r,s}S_0 + \dot{S}'_{0r}\dot{S}_{0s} + \dot{S}'_{0s}\dot{S}_{0r} + S_0'\ddot{S}_{0r,s})y}{2\sigma_0^2 \|S_0^{-1}\|_F^2} \\ &= -\frac{1}{2\sigma_0^2 \|S_0^{-1}\|_F^2} \{\varepsilon'(S_0^{-1'}\ddot{S}'_{0r,s} + \ddot{S}_{0r,s}S_0^{-1})\varepsilon + 2\varepsilon'S_0^{-1'}\dot{S}'_{0s}\dot{S}_{0r}S_0^{-1}\varepsilon\}. \end{aligned} \tag{A.12}$$

The first term in (A.12) has

$$E_{\theta_0}(\varepsilon(S_0^{-1'}\ddot{S}'_{0r,s} + \ddot{S}_{0r,s}S_0^{-1})\varepsilon) = 0$$

and

$$\begin{aligned} \text{Var}_{\theta_0} (\varepsilon (S_0^{-1'} \ddot{S}'_{0r,s} + \ddot{S}_{0r,s} S_0^{-1}) \varepsilon) &= 2\sigma_0^4 \text{tr} (S_0^{-1'} \ddot{S}'_{0r,s} + \ddot{S}_{0r,s} S_0^{-1})^2 \\ &+ \kappa_4 \sum_{i=1}^n [S_0^{-1'} \ddot{S}'_{0r,s} + \ddot{S}_{0r,s} S_0^{-1}]_{i,i}^2. \end{aligned} \tag{A.13}$$

The matrix $\ddot{S}_{0r,s} S_0^{-1}$ is lower triangular with zero diagonal elements, and therefore, the left-hand side of (A.13) is bounded by

$$4\sigma_0^4 \text{tr} (S_0^{-1'} \ddot{S}'_{0r,s} \ddot{S}_{0r,s} S_0^{-1}) = 4\sigma_0^4 \|\ddot{S}_{0r,s} S_0^{-1}\|_F^2 \leq K \|\ddot{S}_{0r,s}\|_2^2 \|S_0^{-1}\|_F^2.$$

Under Assumption A4,

$$\|\ddot{S}_{0r,s}\|_2^2 = \sup_{|x|=1} x' \ddot{S}'_{0r,s} \ddot{S}_{0r,s} Ax = \sup_{|x|=1} x' \ddot{C}'_{0r,s} \ddot{C}_{0r,s} Ax \leq \sup_t \ddot{\beta}_{t,s} \leq K, \tag{A.14}$$

and therefore,

$$\frac{\varepsilon' (S_0^{-1'} \ddot{S}'_{0r,s} + \ddot{S}_{0r,s} S_0^{-1}) \varepsilon}{2\sigma_0^2 \|S_0^{-1}\|_F^2} = O_p \left(\|S_0^{-1}\|_F^{-1} \right). \tag{A.15}$$

The second term on the right-hand side of (A.12) has

$$\begin{aligned} |E_{\theta_0} (2\varepsilon' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon)| &= \sigma_0^2 |\text{tr} (S_0^{-1'} (\dot{S}'_{0s} \dot{S}_{0r} + \dot{S}'_{0r} \dot{S}_{0s}) S_0^{-1})| \\ &= \sigma_0^2 \left\| (\dot{S}'_{0s} \dot{S}_{0r} + \dot{S}'_{0r} \dot{S}_{0s})^{1/2} S_0^{-1} \right\|_F^2 \\ &\leq \sigma_0^2 \left\| (\dot{S}'_{0s} \dot{S}_{0r} + \dot{S}'_{0r} \dot{S}_{0s})^{1/2} \right\|_2^2 \|S_0^{-1}\|_F^2. \end{aligned}$$

Under Assumption A3,

$$\left\| (\dot{S}'_{0s} \dot{S}_{0r} + \dot{S}'_{0r} \dot{S}_{0s})^{1/2} \right\|_2^2 = \sup_{|x|=1} x' (\dot{S}'_{0s} \dot{S}_{0r} + \dot{S}'_{0r} \dot{S}_{0s}) x \leq \sup_t |\dot{\beta}_{0t,r} \dot{\beta}_{0t,s}| \leq K$$

by similar reasoning to (A.14). On the other hand,

$$\begin{aligned} E_{\theta_0} (2\varepsilon' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon) &\geq K_L \text{tr} (S_0^{-1'} S_0^{-1}) \inf_t (\dot{\beta}_{0t,r} \dot{\beta}_{0t,s}) \\ &= K_L \|S_0^{-1}\|_F^2 \inf_t (\dot{\beta}_{0t,r} \dot{\beta}_{0t,s}). \end{aligned} \tag{A.16}$$

Under Assumption A3, $|\inf_t (\dot{\beta}_{0t,r} \dot{\beta}_{0t,s})| < \infty$, and we conclude that

$$-\frac{\varepsilon' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1}\|_F^2} = O_{p,e}(1), \tag{A.17}$$

establishing part (1) of the theorem.

Case 2: $\mu_0 \neq 0$. Showing parts (1) and (2) of the theorem is very similar to the case $\mu_0 = 0$. For $2 \leq r, s \leq m + 1$,

$$\begin{aligned}
 H_{nr,s}^c(\theta_0) &= -\frac{y'(\ddot{S}'_{0r,s}MS_0 + \dot{S}'_{0r}M\dot{S}_{0s} + \dot{S}'_{0s}M\dot{S}_{0r} + S'_0M\ddot{S}_{0r,s})y}{2\sigma_0^2\|S_0^{-1}S_0^{-1}\|_1} \\
 &= -\frac{1}{2\sigma_0^2\|S_0^{-1}S_0^{-1}\|_1}\{\varepsilon'(S_0^{-1}\ddot{S}'_{0r,s}M + M\ddot{S}_{0r,s}S_0^{-1})\varepsilon \\
 &\quad + 2\mu_01'S_0^{-1}\dot{S}'_{0r,s}M\varepsilon + 2\varepsilon'S_0^{-1}\dot{S}'_{0s}M\dot{S}_{0r}S_0^{-1}\varepsilon \\
 &\quad + 4\mu_01'S_0^{-1}\dot{S}'_{0s}M\dot{S}_{0r}S_0^{-1}\varepsilon + 2\mu_0^21'S_0^{-1}\dot{S}'_{0s}M\dot{S}_{0r}S_0^{-1}1\}.
 \end{aligned} \tag{A.18}$$

The first term on the right-hand side of (A.18) has

$$\begin{aligned}
 |E_{\theta_0}(\varepsilon'(S_0^{-1}\ddot{S}'_{0r,s}M + M\ddot{S}_{0r,s}S_0^{-1})\varepsilon)| &= 2\sigma_0^2|\text{tr}(P\ddot{S}_{0r,s}S_0^{-1})| \\
 &\leq 2\sigma_0^2\|P\|_F\|\ddot{S}_{0r,s}S_0^{-1}\|_F \\
 &\leq 2\sigma_0^2\|\ddot{S}_{0r,s}\|_2\|S_0^{-1}\|_F \\
 &\leq K\|S_0^{-1}\|_F,
 \end{aligned}$$

because of (A.14). With similar calculations, we see that

$$\text{Var}_{\theta_0}(\varepsilon'(S_0^{-1}\ddot{S}'_{0r,s}M + M\ddot{S}_{0r,s}S_0^{-1})\varepsilon) \leq K\|S_0^{-1}\|_F^2$$

and therefore,

$$\frac{\varepsilon'(S_0^{-1}\ddot{S}'_{0r,s}M + M\ddot{S}_{0r,s}S_0^{-1})\varepsilon}{\|S_0^{-1}S_0^{-1}\|_1} = O_p(\rho_n\|S_0^{-1}\|_F^{-1}),$$

which is asymptotically negligible.

The term $2\mu_01'S_0^{-1}\dot{S}'_{0r,s}M\varepsilon$ in (A.18) has zero expectation and

$$\begin{aligned}
 \text{Var}_{\theta_0}(2\mu_01'S_0^{-1}\dot{S}'_{0r,s}M\varepsilon) &= 4\mu_0^2\sigma_0^21'S_0^{-1}\dot{S}'_{0r,s}M\ddot{S}_{0r,s}S_01 \\
 &\leq 4\mu_0^2\sigma_0^2\|S_0^{-1}S_0^{-1}\|_1\|\dot{S}'_{0r,s}M\ddot{S}_{0r,s}\|_2 \\
 &\leq K\|S_0^{-1}S_0^{-1}\|_1,
 \end{aligned}$$

implying that

$$\frac{2\mu_01'S_0^{-1}\dot{S}'_{0r,s}M\varepsilon}{\|S_0^{-1}S_0^{-1}\|_1} = O_p(\|S_0^{-1}S_0^{-1}\|_1^{-1/2}),$$

which is also asymptotically negligible.

For the third term on the right-hand side of (A.18),

$$\varepsilon'S_0^{-1}\dot{S}'_{0s}M\dot{S}_{0r}S_0^{-1}\varepsilon = \varepsilon'S_0^{-1}\dot{S}'_{0s}\dot{S}_{0r}S_0^{-1}\varepsilon - \varepsilon'S_0^{-1}\dot{S}'_{0s}P\dot{S}_{0r}S_0^{-1}\varepsilon. \tag{A.19}$$

By (A.17), the first term on the right-hand side of (A.19) is $O_{p,e}(\|S_0^{-1}\|_F^2)$, and for the second term, we have

$$\begin{aligned} |E_{\theta_0}(\varepsilon' S_0^{-1'} \dot{S}'_{0s} P \dot{S}_{0r} S_0^{-1} \varepsilon)| &= \frac{\sigma_0^2}{n} |1' \dot{S}_{0r} S_0^{-1} S_0^{-1'} \dot{S}'_{0s} 1| \\ &\leq \frac{K}{n} 1' (S_0^{-1} - I_n) (S_0^{-1} - I_n)' 1 \\ &\leq \frac{K}{n} (1' S_0^{-1} S_0^{-1'} 1 + 21' S_0^{-1} 1 + n). \end{aligned} \tag{A.20}$$

Now,

$$1' S_0^{-1} S_0^{-1'} 1 \leq n \|S_0^{-1} S_0^{-1'}\|_2 \leq n \|S_0^{-1}\|_2^2 \leq n \|S_0^{-1}\|_F^2,$$

and $1' S_0^{-1} 1 \leq \sqrt{n} \|S_0^{-1'} S_0^{-1}\|_1^{1/2}$. Therefore, (A.20) is less than or equal to

$$K \left(\|S_0^{-1}\|_F^2 + \frac{2}{\sqrt{n}} \|S_0^{-1'} S_0^{-1}\|_1^{1/2} + 1 \right). \tag{A.21}$$

With a $\|S_0^{-1'} S_0^{-1}\|_1^{-1}$ normalization, the dominant term in (A.21) is bounded by $K\rho_n$. Similar calculations reveal the variance of $\varepsilon' S_0^{-1'} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} \varepsilon$ to be of the order $O(\|S_0^{-1}\|_F^4)$. Together with the exact order of the first term on the right-hand side of (A.19), it follows that

$$-\frac{\varepsilon' S_0^{-1'} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1} = O_{p,e}(\rho_n).$$

The fourth term on the right-hand side of (A.18) equals

$$4\mu_0 1' S_0^{-1'} \dot{S}'_{0s} (I_n - P) \dot{S}_{0r} S_0^{-1} \varepsilon, \tag{A.22}$$

which has zero expectation. Also,

$$\begin{aligned} \text{Var}_{\theta_0}(4\mu_0 1' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon) &= 16\mu_0^2 \sigma_0^2 1' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0s} S_0^{-1} 1 \\ &\leq K 1' (S_0^{-1'} S_0^{-1})^2 1 \\ &\leq \|S_0^{-1'} S_0^{-1}\|_1 \|S_0^{-1} S_0^{-1'}\|_2 \\ &\leq \|S_0^{-1'} S_0^{-1}\|_1 \|S_0^{-1}\|_F^2. \end{aligned} \tag{A.23}$$

Under Assumption A3, it is also true that

$$\text{Var}_{\theta_0}(4\mu_0 1' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon) \geq K_L 1' (S_0^{-1'} S_0^{-1})^2 1.$$

With tedious albeit straightforward calculations, we obtain

$$\frac{(1' (S_0^{-1'} S_0^{-1})^2 1)^{1/2}}{\|S_0^{-1'} S_0^{-1}\|_1} = O_e(1), \text{ if } \beta_t = \beta > 1, \forall t,$$

and

$$\frac{\left(1' (S_0^{-1'}) S_0^{-1} 1\right)^{1/2}}{\|S_0^{-1'} S_0^{-1}\|_1} = o(1), \text{ if } 0 \leq \beta_t = \beta < 1, \forall t.$$

In general though, the bound in (A.23) implies that

$$\frac{4\mu_0 1' S_0^{-1'} \dot{S}'_{0s} \dot{S}_{0r} S_0^{-1} \varepsilon}{\|S_0^{-1'} S_0^{-1}\|_1} = O_p(\sqrt{\rho_n}).$$

The second term in (A.22) has zero expectation and

$$\begin{aligned} \text{Var}_{\theta_0} (4\mu_0 1' S_0^{-1'} \dot{S}'_{0s} P \dot{S}_{0r} S_0^{-1} \varepsilon) &= 16\mu_0^2 \sigma_0^2 1' S_0^{-1'} \dot{S}'_{0s} P \dot{S}_{0r} S_0^{-1} S_0^{-1'} \dot{S}'_{0r} P \dot{S}_{0s} S_0^{-1} 1 \\ &\leq K \|S_0^{-1'} S_0^{-1}\|_1 \|\dot{S}'_{0s} P \dot{S}_{0r} S_0^{-1} S_0^{-1'} \dot{S}'_{0r} P \dot{S}_{0s}\|_2 \\ &\leq \|S_0^{-1'} S_0^{-1}\|_1 \|S_0^{-1}\|_F^2. \end{aligned}$$

We recall that in both of the cases $\beta_t = \beta > 1, \forall t$, and $0 \leq \beta_t = \beta < 1, \forall t, \rho_n = O_e(1)$. The implication is that

$$-\frac{2\mu_0 1' S_0^{-1'} \dot{S}'_{0s} M \dot{S}_{0r} S_0^{-1} \varepsilon}{\sigma_0^2 \|S_0^{-1'} S_0^{-1}\|_1} = O_p(\sqrt{\rho_n}), \tag{A.24}$$

and it is emphasized that the bound is an upper one and not an exact one. Specifically, in the fixed coefficient explosive case, the bound is also exact whereas in the fixed coefficient stationary case, the upper bound is not exact, and in fact, it holds that in this case (A.24) is $o_p(1)$.

The last term in (A.18) was shown to be $O_e(1)$ in Lieberman (2012). □

Proof of Lemma 4

Case 1: $\mu_0 = 0$. The terms $[A_n]_{1,1}$ and $[A_n]_{1,r}, r = 2, \dots, m + 1$, are given in (A.6) and in the proof of Theorem 3 respectively. The term $[A_n]_{2 \leq r, s \leq m+1}$ follows from (12) and (A.7) and because the diagonal of Λ_{0r} is equal to zero.

Case 2: $\mu_0 \neq 0$. The treatment of the terms $[A_n^c]_{1,1}$ and $[A_n^c]_{1,r}$ is similar to the previous case, the additional $o(1)$ arising from the fact that $\text{tr}(M) = n - 1$. For $r, s = 2, \dots, m + 1$, we use the following facts:

$$\text{Cov}_{\theta_0} (QF_{nr}^c, QF_{ns}^c) = 2\sigma_0^4 \text{tr}(\Gamma_{0r} \Gamma_{0s}) + \kappa_4 \sum_{i=1}^n [\Gamma_{0r}]_{i,i} [\Gamma_{0s}]_{i,i}$$

$$\text{Cov}_{\theta_0} (LF_{nr}^c, LF_{ns}^c) = \sigma_0^2 b'_{0r} b_{0s},$$

and

$$\text{Cov}_{\theta_0} (QF_{nr}^c, LF_{ns}^c) = \kappa_3 \sum_{i=1}^n [\Gamma_{0r}]_{i,i} [b_{0s}]_i.$$

Moreover, $E_{\theta_0}(LF_{nr}^c) = 0$, and

$$|E_{\theta_0}(QF_{nr}^c)| = 2\sigma_0^2 |\text{tr}(P \dot{S}_{0r} S_0^{-1})| \leq \frac{K}{n} 1'(S_0^{-1} - I_n) 1.$$

However, $1'S_0^{-1}1 \leq \sqrt{n} \|S_0^{-1'} S_0^{-1}\|_1^{1/2}$, implying that

$$\frac{|E_{\theta_0}(QF_{nr}^c)|}{\|S_0^{-1'} S_0^{-1}\|_1^{1/2}} \leq \frac{K}{\sqrt{n}}$$

and therefore,

$$\frac{1}{\|S_0^{-1'} S_0^{-1}\|_1} \text{Cov}_{\theta_0}(QF_{nr}^c, QF_{ns}^c) = \frac{1}{\|S_0^{-1'} S_0^{-1}\|_1} E_{\theta_0}(QF_{nr}^c QF_{ns}^c) + O\left(\frac{1}{n}\right).$$

The proof is completed on the observation of (18) and (19). □

Lemma 7. Under Assumptions A0–A4, for all $j, k, l = 1, \dots, m + 1$ and uniformly in Θ ,

$$D_n \frac{\partial^3 l_n(\theta)}{\partial \theta_j \partial \theta_k \partial \theta_l} D_n = O_p(1) \text{ and } D_n^c \frac{\partial^3 l_n^c(\theta)}{\partial \theta_j \partial \theta_k \partial \theta_l} D_n^c = O_p(1).$$

Proof of Lemma 7

It will be sufficient to consider derivatives w.r.t. the θ_2 components. For the case $\mu_0 = 0$, for $j, k, l = 2, \dots, m + 1$,

$$\begin{aligned} \frac{\partial^3 l_n(\theta)}{\partial \theta_j \partial \theta_k \partial \theta_l} &= -\frac{1}{2\sigma^2} y' (\ddot{S}'_{j,k,l} S + \ddot{S}'_{j,k} \dot{S}_l + \ddot{S}'_{j,l} \dot{S}_k + \dot{S}'_j \ddot{S}_{k,l} \\ &\quad + \ddot{S}'_{k,l} \dot{S}_j + \dot{S}'_k \ddot{S}_{j,l} + \dot{S}'_l \ddot{S}_{j,k} + S' \ddot{S}_{j,k,l}) y, \end{aligned} \tag{A.25}$$

and therefore, we need to show that for $p = 1, 2$,

$$\begin{aligned} |\text{tr}(S_0^{-1'} (\ddot{S}'_{j,k,l} S + \ddot{S}'_{j,k} \dot{S}_l + \ddot{S}'_{j,l} \dot{S}_k + \dot{S}'_j \ddot{S}_{k,l} + \ddot{S}'_{k,l} \dot{S}_j \\ + \dot{S}'_k \ddot{S}_{j,l} + \dot{S}'_l \ddot{S}_{j,k} + S' \ddot{S}_{j,k,l}) S_0^{-1})^p| \leq K \|S_0^{-1}\|^p, \end{aligned} \tag{A.26}$$

uniformly in Θ . Denote by S^* a derivative of S w.r.t. any θ_2 component. We observe that the terms in (A.26) are either of the form

$$\left| \text{tr} \left((S_0^{-1'} (S^{*'} S^*) S_0^{-1})^p \right) \right|$$

or

$$\left| \text{tr} \left((S_0^{-1'} (S^{*'} S + S' S^*) S_0^{-1})^p \right) \right|.$$

Under Assumptions A3 and A4, both terms are uniformly bounded by $K \|S_0^{-1}\|^p$ by very similar arguments used in the proofs of Theorems 2 and 3. For the $\mu_0 \neq 0$ case, instead of replacing y by $S_0^{-1} \varepsilon$ in (A.25), we replace it by $\mu_0 S_0^{-1} 1 + S_0^{-1} \varepsilon$ and again use similar reasoning to obtain a uniform $O_p(\|S_0^{-1'} S_0^{-1}\|_1)$ bound. □

Proof of Theorem 5

We shall deal with the $\mu_0 \neq 0$ case only – the complementary case is very similar. For part (2), we write

$$\text{vech}(H_n(\tilde{\theta}_n)) = \text{vech}(H_n(\theta_0)) + \frac{\partial \text{vech}(H_n(\tilde{\theta}_n))}{\partial \theta'} (\tilde{\theta}_n - \theta_0),$$

where $\|\tilde{\theta}_n - \theta_0\| \leq \|\hat{\theta}_n - \theta_0\|$ and $\text{vech}(\cdot)$ is the operator that vectorizes the lower half, including the main diagonal, of a symmetric matrix. By virtue of Theorem 3, $\text{vech}(H_n(\theta_0)) = O_p(1)$. By Theorem 1, the mean value $\tilde{\theta}_n$ satisfies $\tilde{\theta}_n - \theta_0 = o_p(1)$. Under Assumption A4, with very similar calculations to the proof of Theorem 3, which we omit for brevity, $\partial \text{vech}(H_n(\tilde{\theta}_n))/\partial \theta'$ is uniformly bounded. Therefore,

$$\text{vech}(H_n(\tilde{\theta}_n)) = \text{vech}(H_n(\theta_0)) + o_p(1).$$

The theorem is established by an application of Lemma 2.4(a) of Hayashi (2000) and using Lemma 7. □

Proof of Theorem 6

The model is $S_0 y = \mu_0 1 + \varepsilon$, and therefore,

$$\mu_0 = \frac{1' S_0 y}{n} - \bar{\varepsilon}_n,$$

where $\bar{\varepsilon}_n = \sum_{t=1}^n \varepsilon_t$. Hence,

$$\begin{aligned} \hat{\mu}_n - \mu_0 &= \frac{1' (S(\hat{\theta}_n) - S(\theta_0)) y}{n} + \bar{\varepsilon}_n \\ &= \sum_{r=2}^{m+1} (\hat{\theta}_{nr} - \theta_{0r}) \frac{1' \dot{S}_r(\tilde{\theta}_n) y}{n} + \bar{\varepsilon}_n, \end{aligned}$$

where $\tilde{\theta}_n$ satisfies $\|\tilde{\theta}_n - \hat{\theta}_n\| \leq \|\hat{\theta}_n - \theta_0\|$. Under Assumptions A2 and A3,

$$\begin{aligned} |1' \dot{S}_r(\tilde{\theta}_n) y| &= |1' \dot{S}_r(\tilde{\theta}_n) (\mu_0 S_0^{-1} 1 + S_0^{-1} \varepsilon)| \\ &\leq \sqrt{1' \dot{C}_r(\tilde{\theta}_n)' \dot{C}_r(\tilde{\theta}_n) 1} \left(\mu_0 \sqrt{1' S_0^{-1} S_0^{-1} 1} + \sqrt{\varepsilon' S_0^{-1} S_0^{-1} \varepsilon} \right) \\ &\leq K \sqrt{n} \left(\mu_0 \|S_0^{-1} S_0^{-1}\|_1^{1/2} + O_p(\|S_0^{-1}\|_F) \right). \end{aligned}$$

It follows that

$$|\hat{\mu}_n - \mu_0| \leq \frac{K}{\sqrt{n}} \left(\mu_0 \|S_0^{-1} S_0^{-1}\|_1^{1/2} + O_p(\|S_0^{-1}\|_F) \right) \sum_{r=2}^{m+1} |\hat{\theta}_{nr} - \theta_{0r}| + |\bar{\varepsilon}_n|.$$

By (20) and Theorems 2 and 3, $D_n^{-1}(\hat{\theta}_n - \theta_0) = O_{p,e}(1)$, if $\mu_0 = 0$, and $(D_n^c)^{-1}(\hat{\theta}_n - \theta_0) = O_{p,e}(1)$, if $\mu_0 \neq 0$. This implies that

$$\begin{aligned} |\hat{\mu}_n - \mu_0| &\leq \frac{K}{\sqrt{n}} + |\bar{\varepsilon}_n|, \text{ if } \mu_0 = 0, \\ |\hat{\mu}_n - \mu_0| &\leq \frac{K}{\sqrt{n}} (\mu_0 + \rho_n^{1/2}) + |\bar{\varepsilon}_n|, \text{ if } \mu_0 \neq 0, \end{aligned}$$

and the proof is completed. □